# Deep learning and realistic datasets

Zhongqi Miao, Ziwei Liu

#### Summary

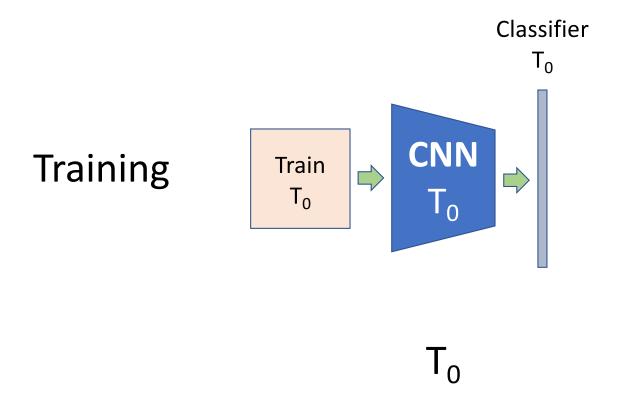
- Background
- Large-scale long-tailed recognition in an open world
- Open compound domain adaptation

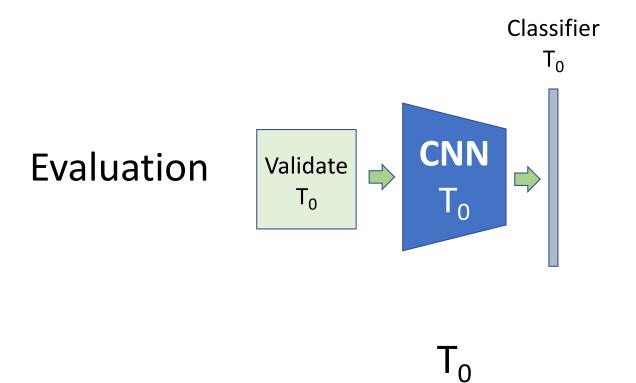
# Background

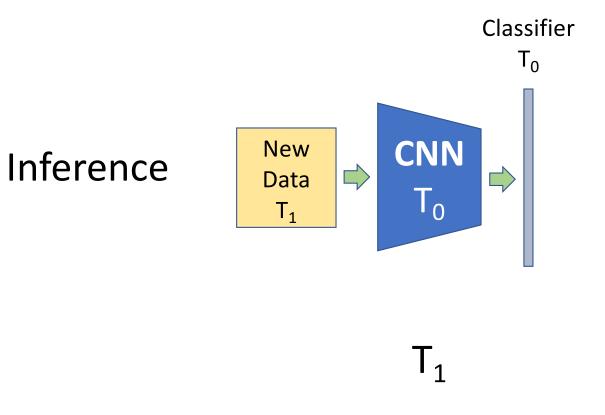
• Deep learning looks so powerful!!

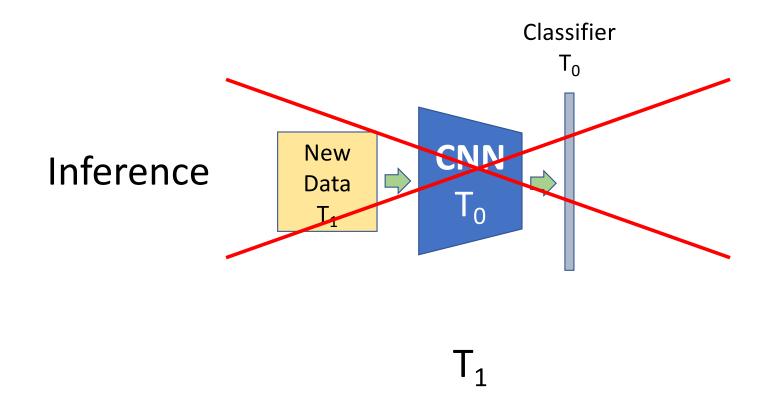


• Even the state-of-the-art methods are not good enough to handle **realistic data** in **realistic settings**!

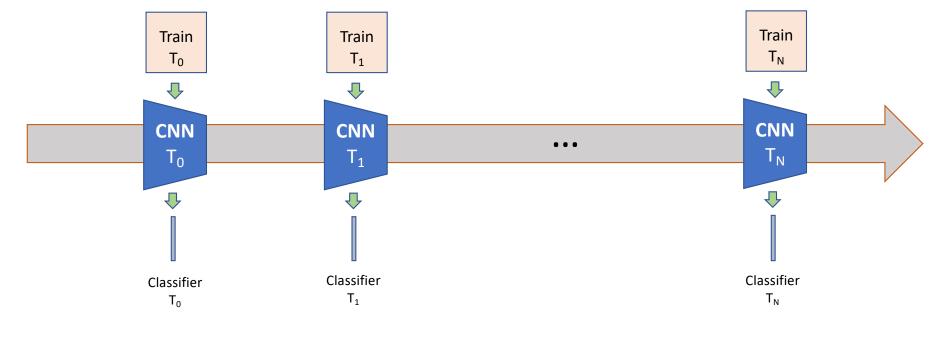




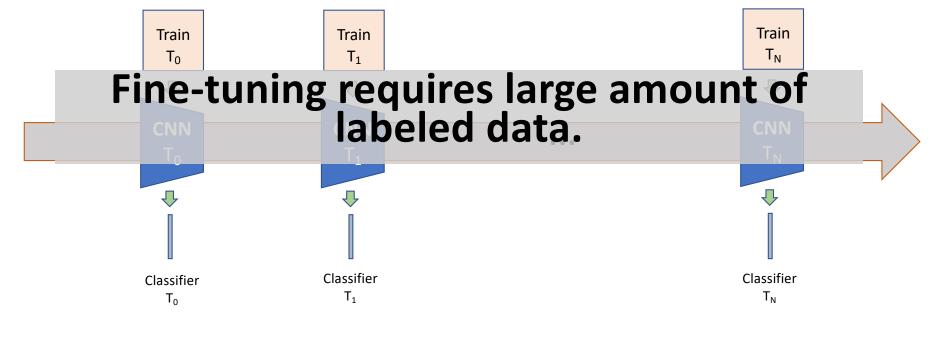




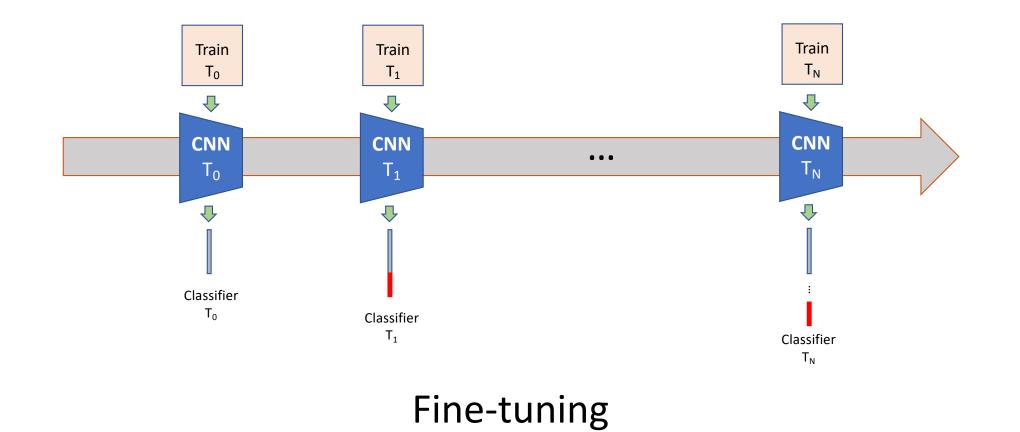
- Long-tailed
- Open-ended
- Multi-domain

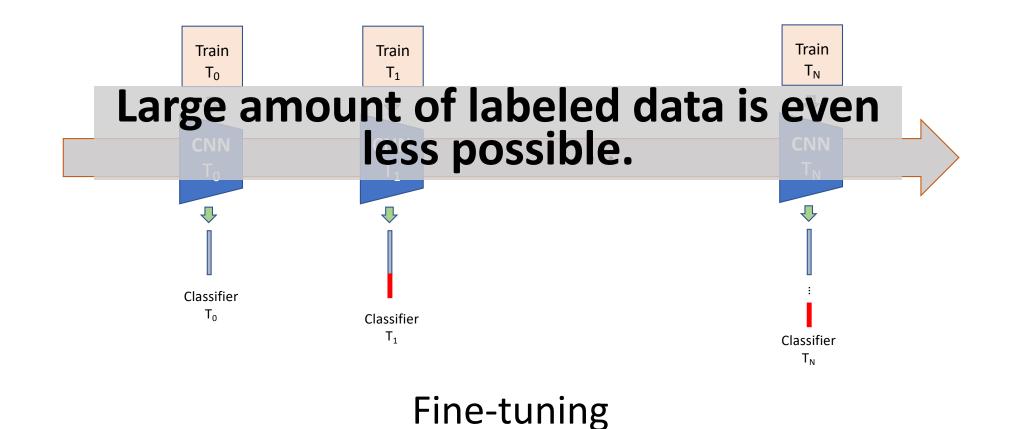


Fine-tuning

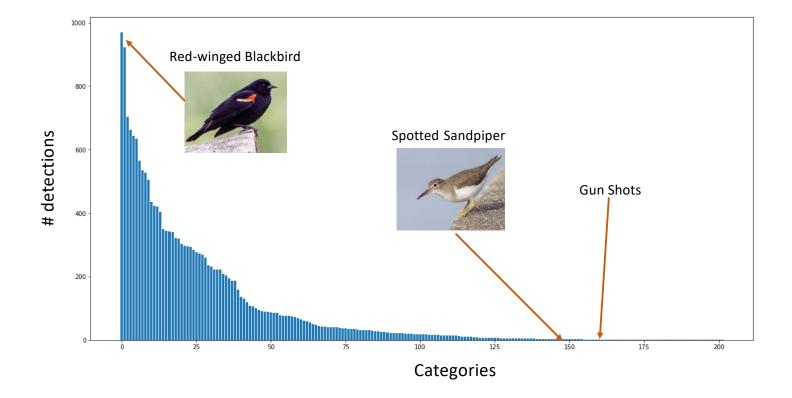


**Fine-tuning** 

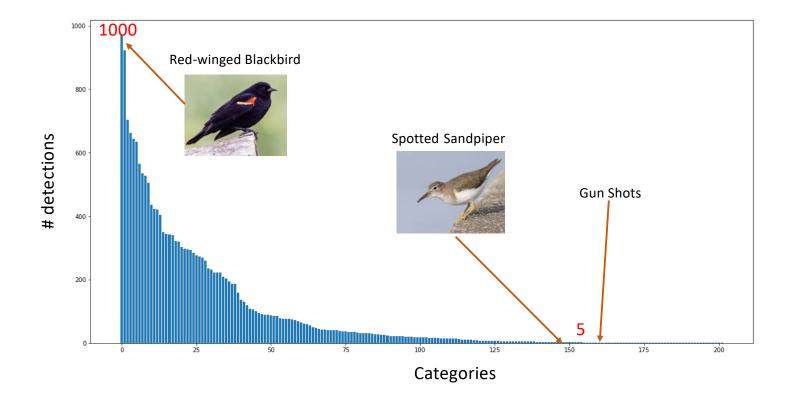




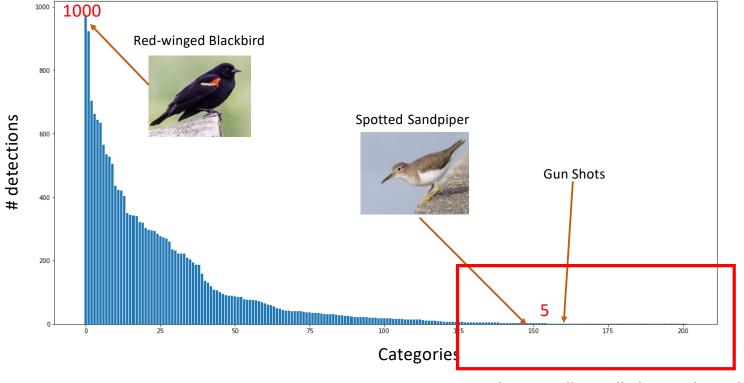
# Long-tailed distribution



# Long-tailed distribution



# Open!



New classes will usually be on this side

- Long-tailed
- Open-ended
- Multi-domain

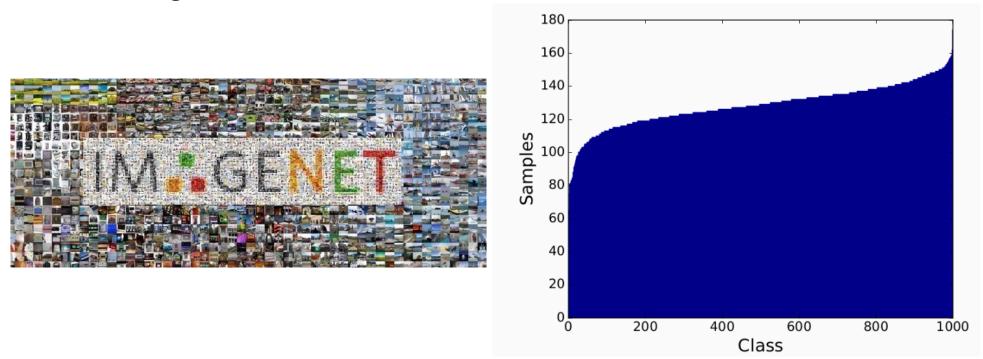
### Open long-tailed recognition

Ziwei Liu<sup>1,2\*</sup> Zhongqi Miao<sup>2\*</sup> Xiaohang Zhan<sup>1</sup> Jiayun Wang<sup>2</sup> Boqing Gong<sup>3,2†</sup> Stella X. Yu<sup>2</sup> 1. The Chinese University of Hong Kong 2. UC Berkeley / ICSI 3. Google Inc.

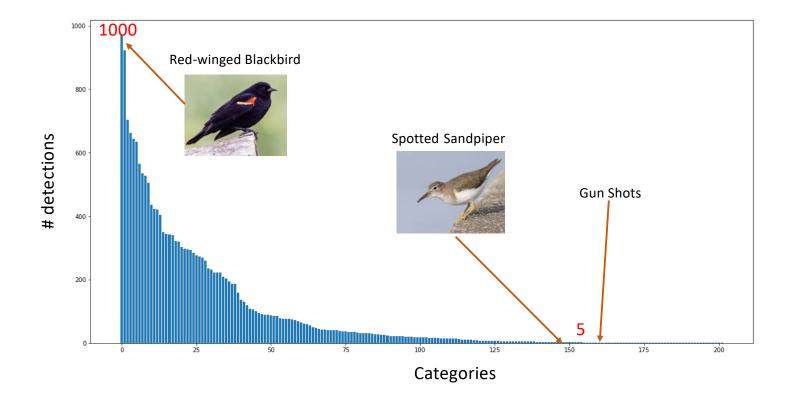
CVPR, 2019, oral

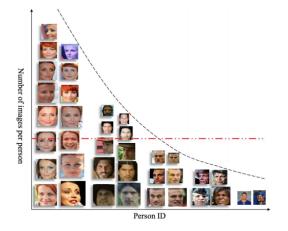
# Long-tailed distribution

• Modern deep learning techniques are based on large-scale balanced training datasets:

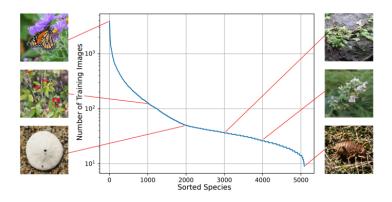


# Long-tailed distribution

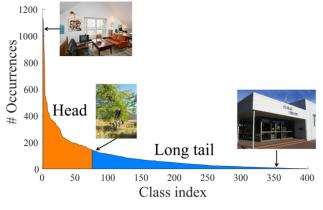




Faces [Zhang et al. 2017]



Species [Van Horn et al. 2019]

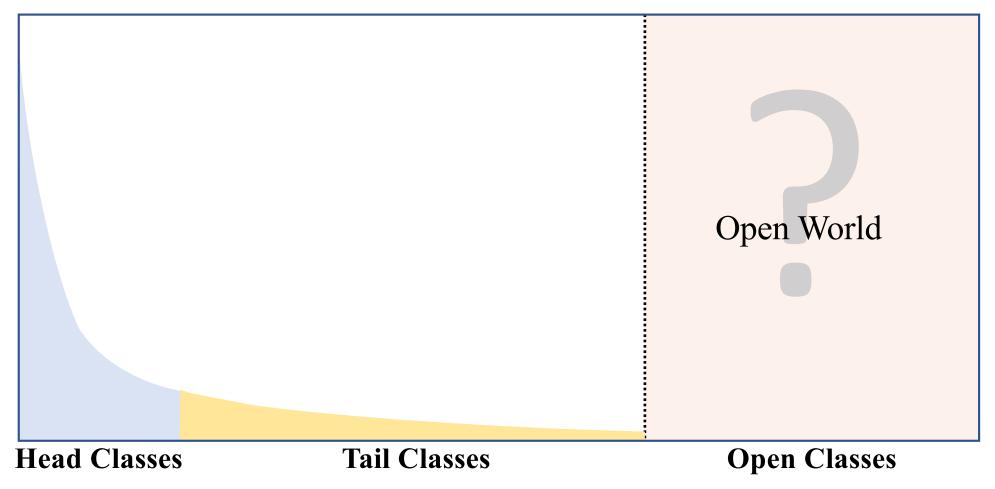


Places [Wang et al. 2017]

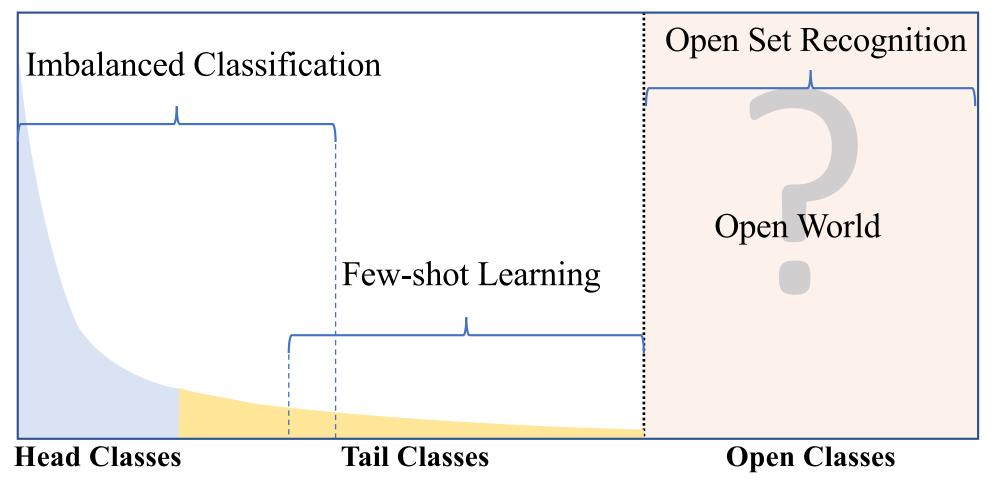


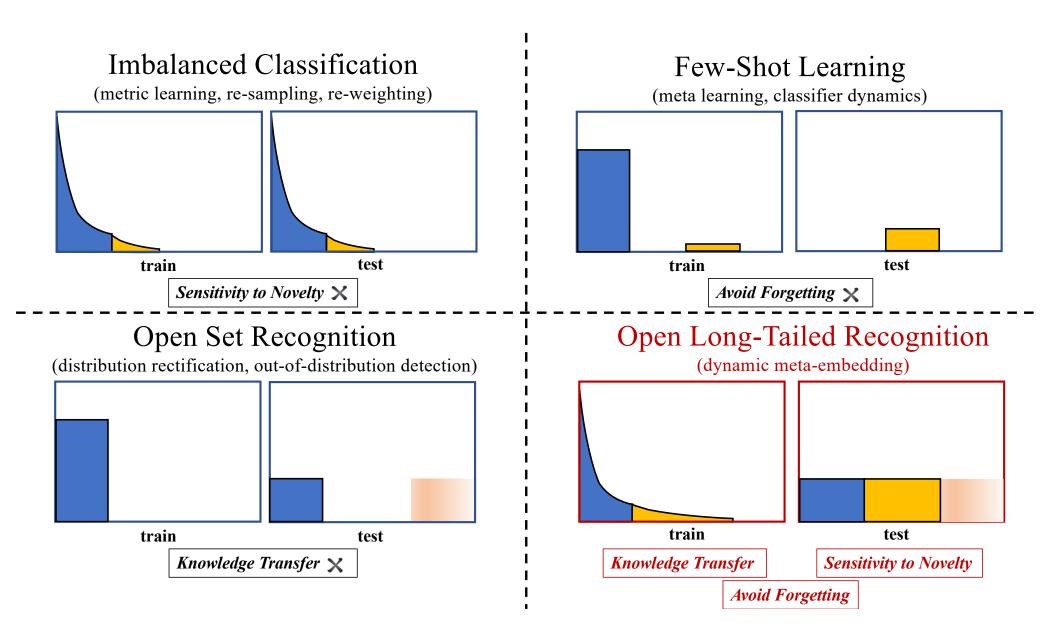
Actions [Zhang et al. 2019]

#### **Open Long-Tailed Recognition**

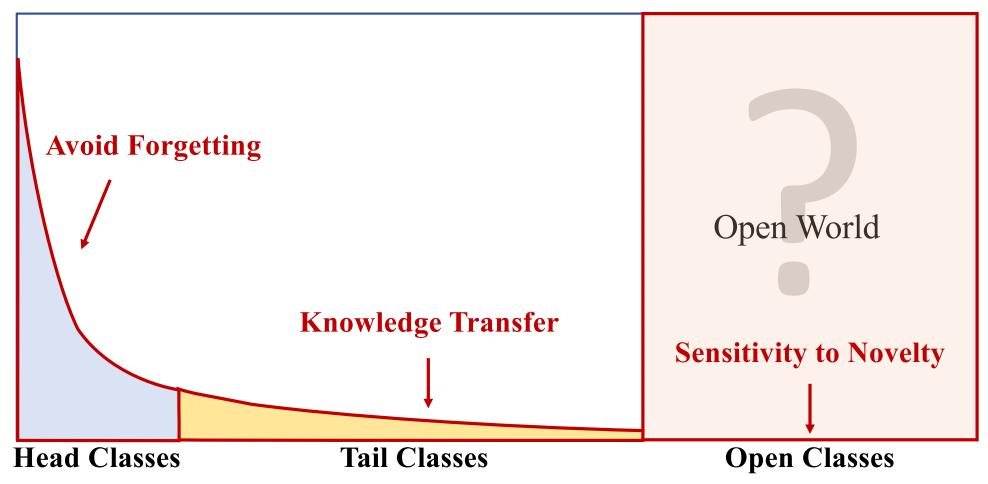


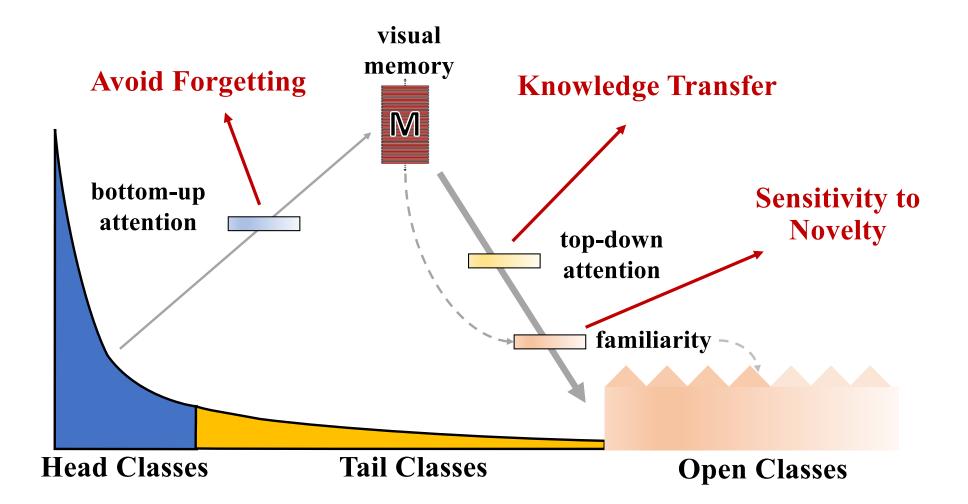
#### **Open Long-Tailed Recognition**

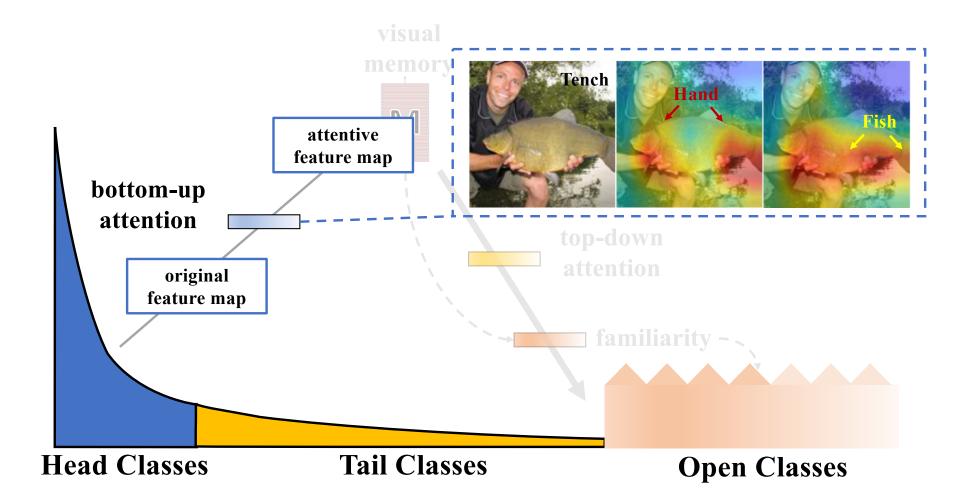




#### **Open Long-Tailed Recognition**







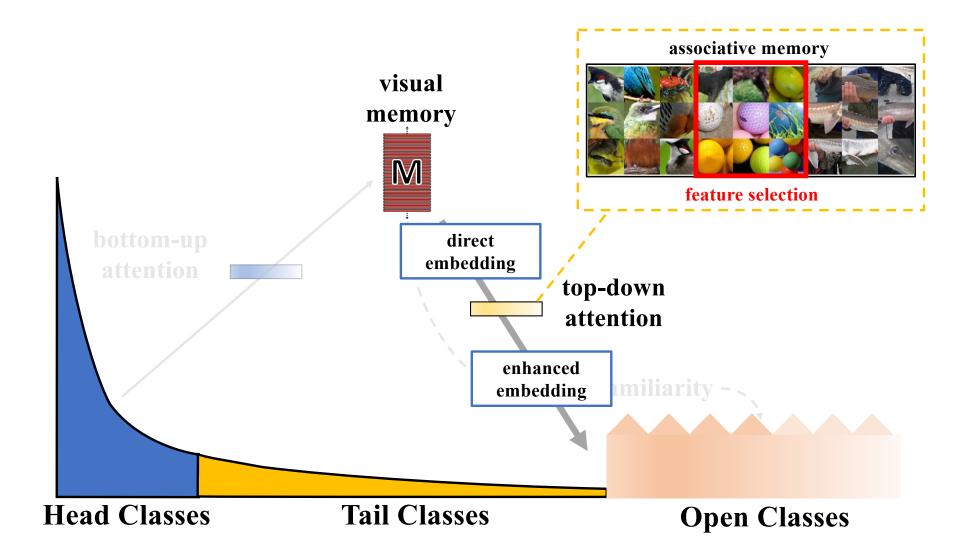


(b.1) Input Image

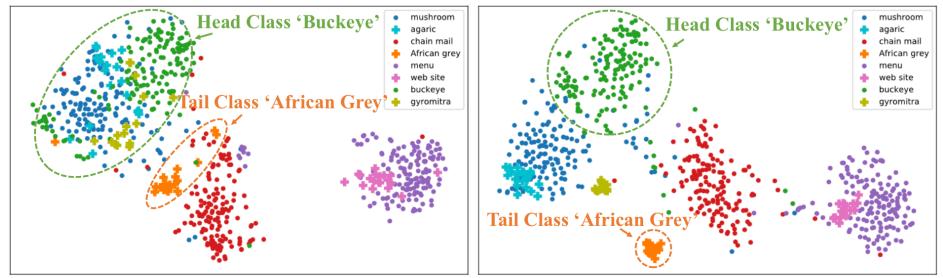
(b.2) Feature Map of Plain ResNet Model



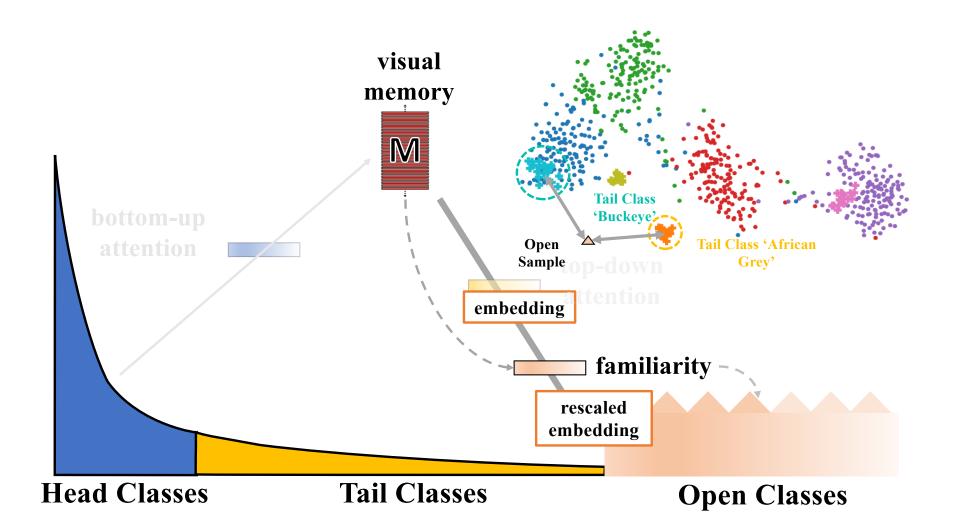
(b.3) Feature Map of (b.4) Modulated Our Model Attention

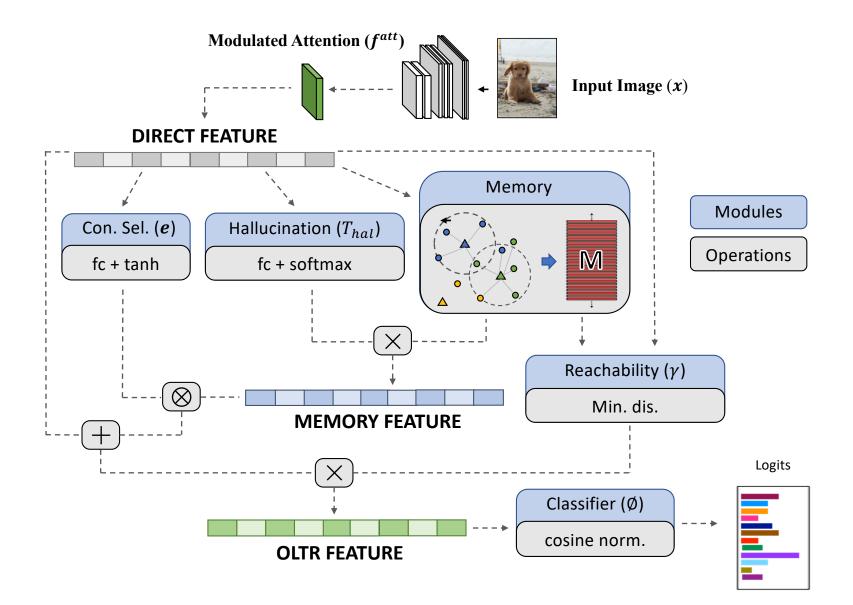


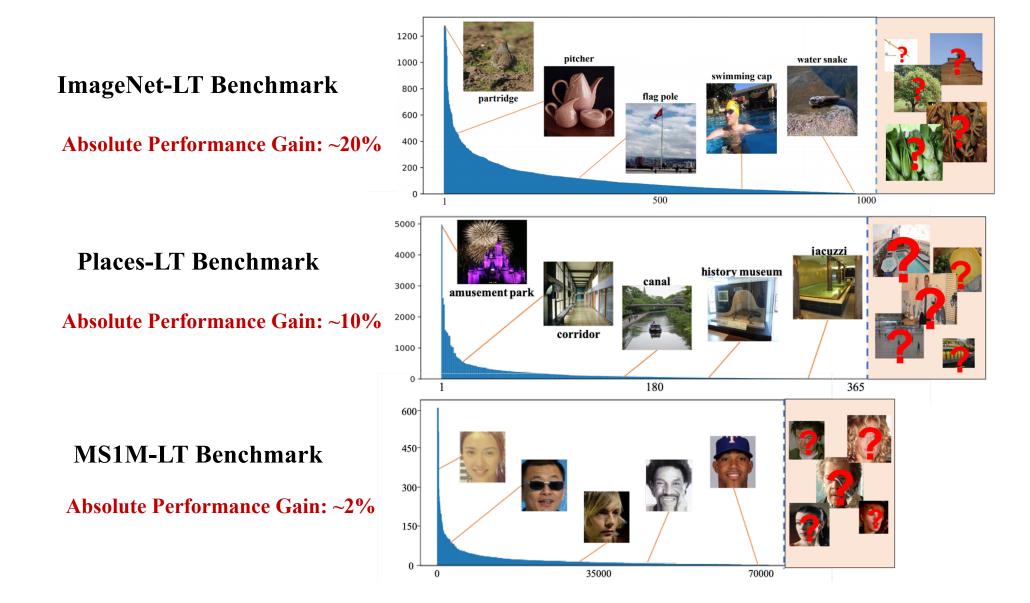


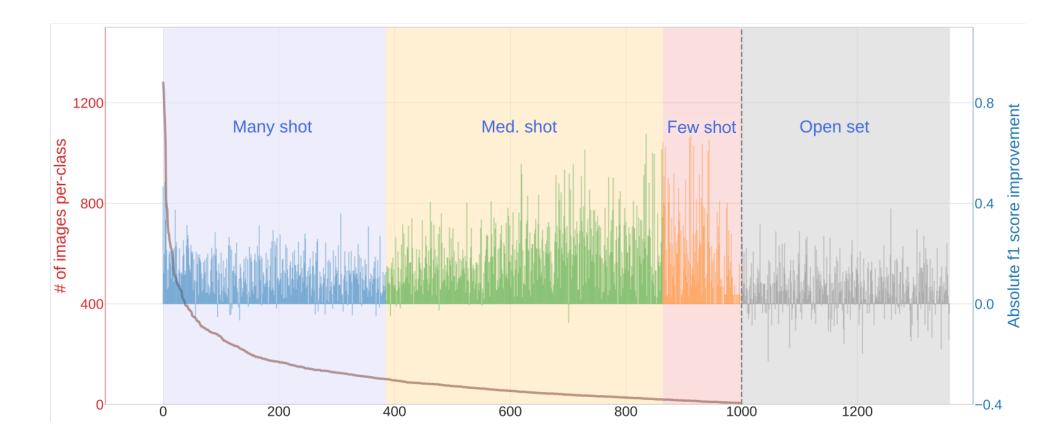


(a) Embedding of Plain ResNet Model (b) Embedding of Dynamic Meta-Embedding









#### Open compound domain adaptation

Ziwei Liu\*, Zhongqi Miao\*, Xingang Pan, Xiaohang Zhan, Dahua Lin, Stella X. Yu, Boqing Gong The Chinese University of Hong Kong & UC Berkeley / ICSI & Google Inc.

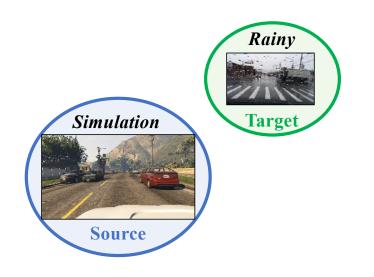
CVPR, 2020, oral

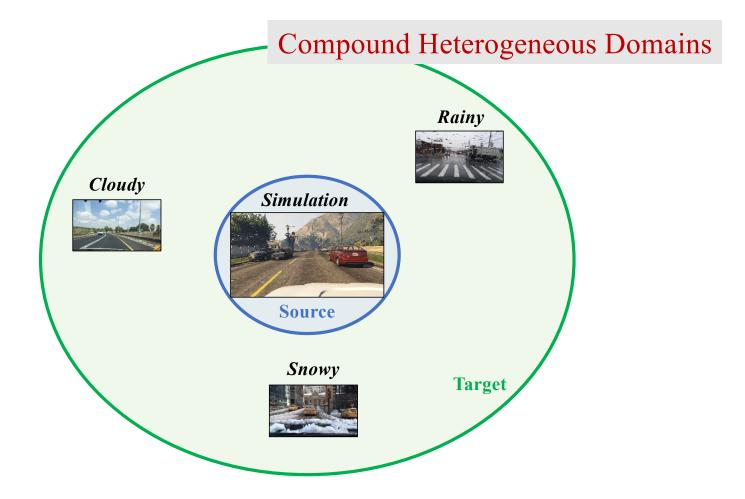
#### Simulation

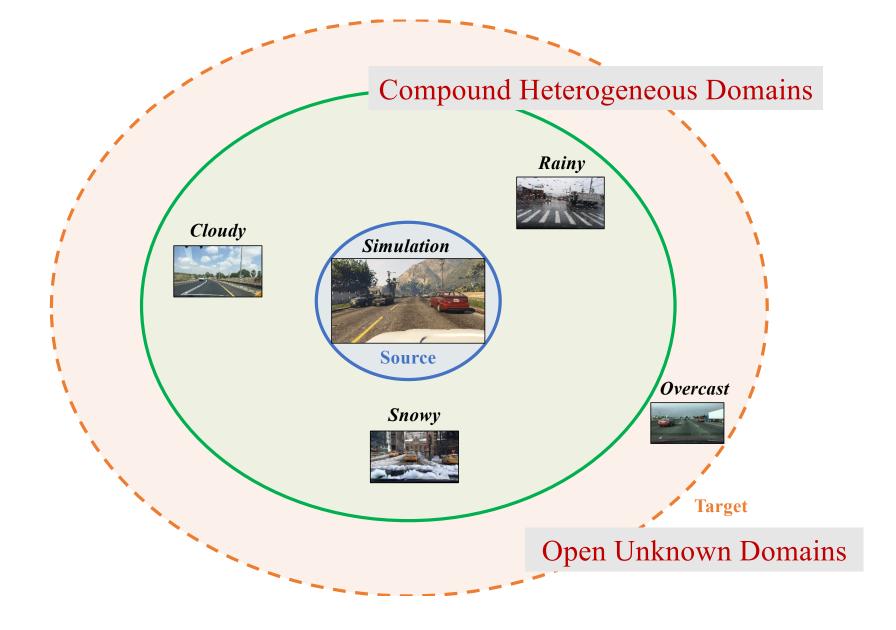


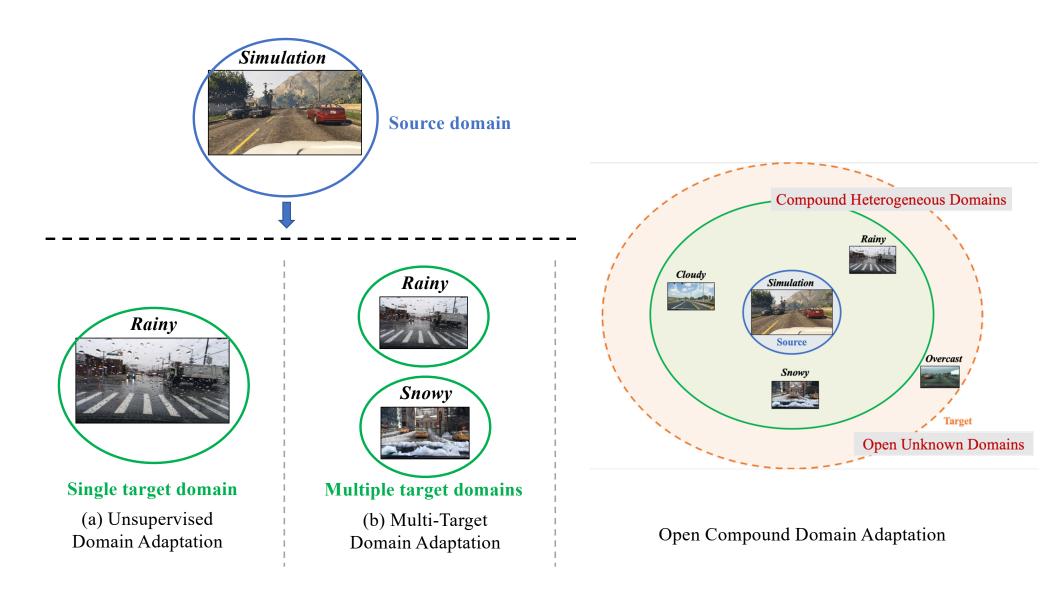
### Open World Driving Conditions

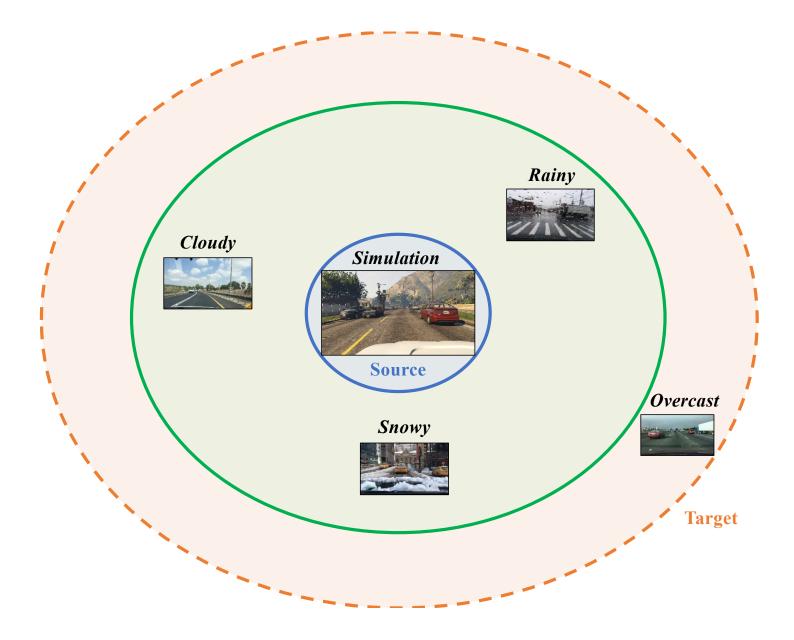














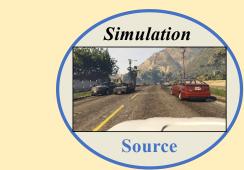
Cloudy

## **Overcast**









#### Foggy









## Rainy

Cloudy



Source







#### Foggy



# After-rain



## Rainy

Cloudy



Simulation

Source

#### Snowy



Flooded

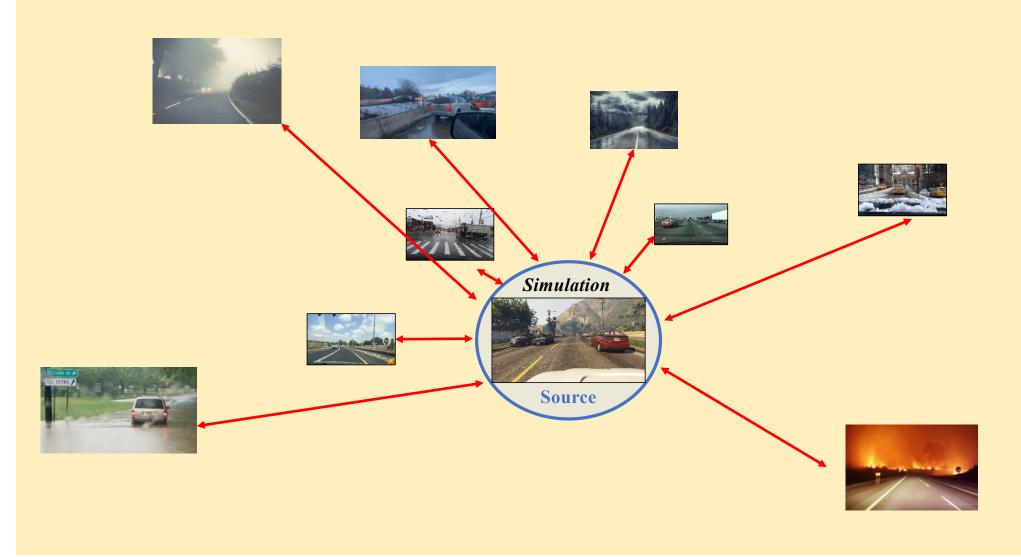


Fire



. . .







#### **Compound Targets**

**Open Targets** 

#### Simulation





Cloudy



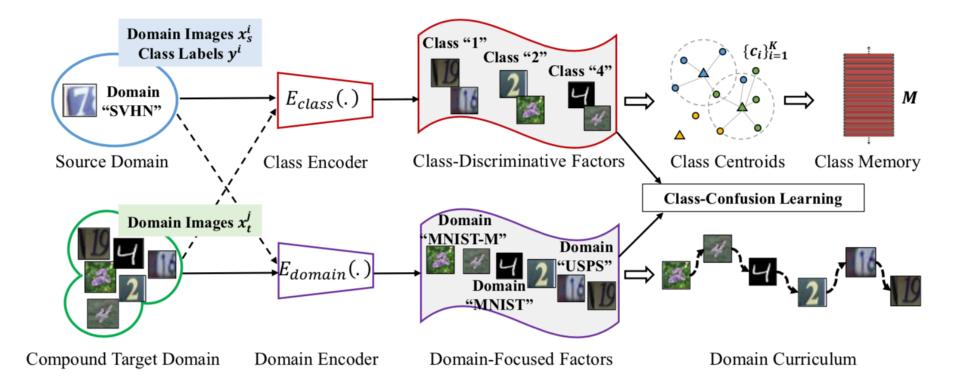
**Open World Driving Conditions** 

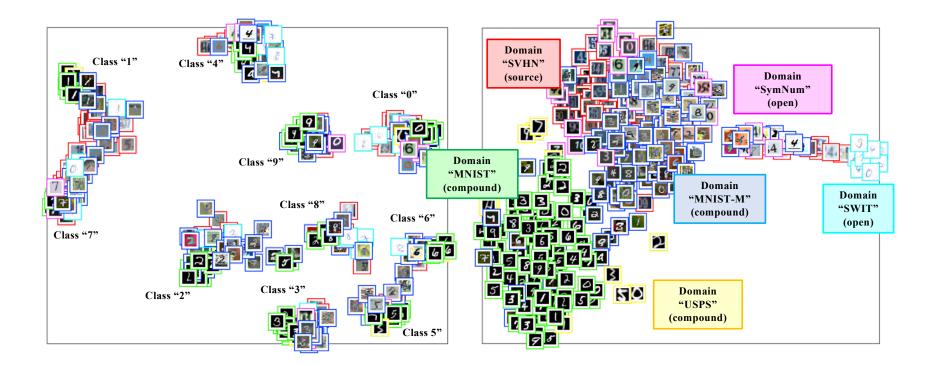
Rainy

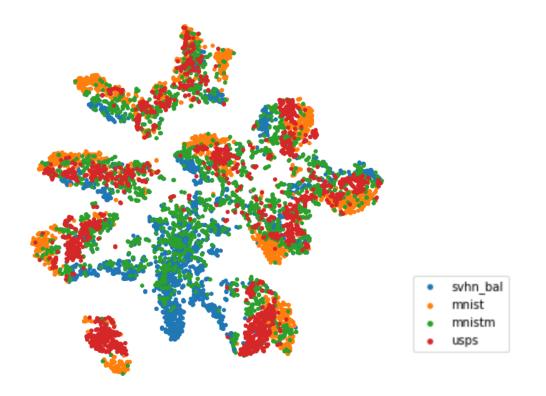


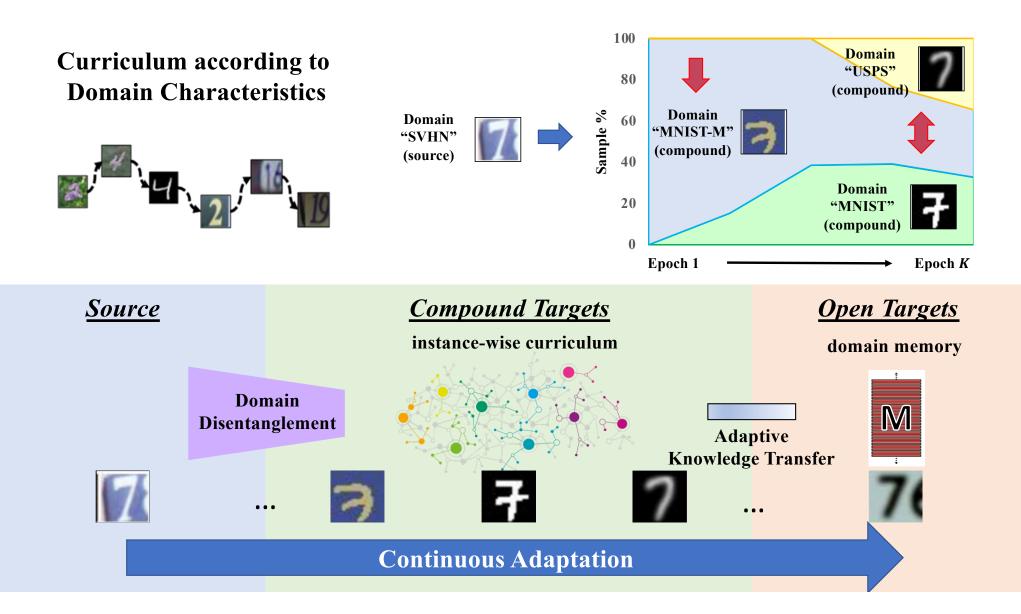
Overcast

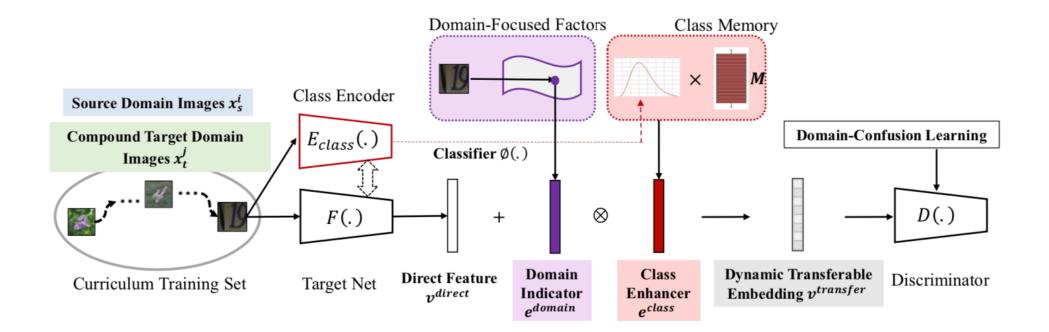






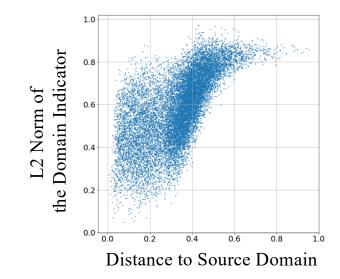






#### **Memory-Augmented Domain Indicator**

 $v_{transfer} = v_{direct} + e_{domain} \otimes v_{enhance}$ 





#### **Compound Targets**

**Open Targets** 

#### Simulation





Cloudy



**Open World Driving Conditions** 

Rainy

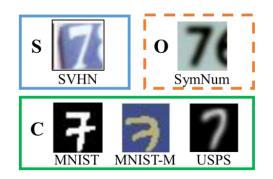


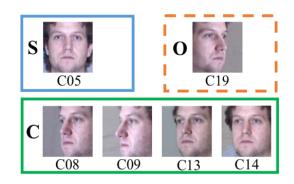
Overcast

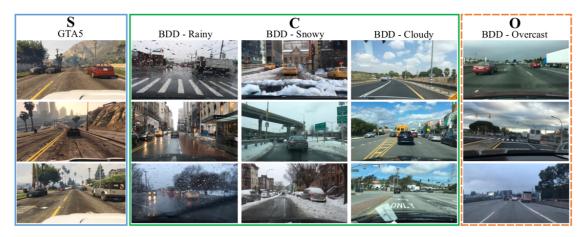


C-Digits Benchmark Absolute Performance Gain: ~5%

C-Faces Benchmark Absolute Performance Gain: ~10%

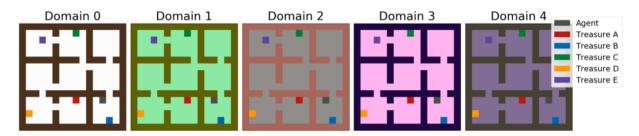




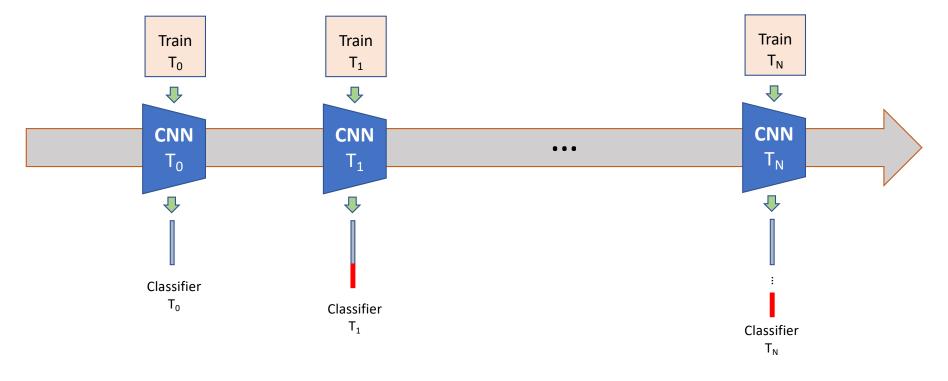


C-Driving Benchmark Absolute Performance Gain: ~2%

C-Mazes Benchmark Absolute Performance Gain: ~30%

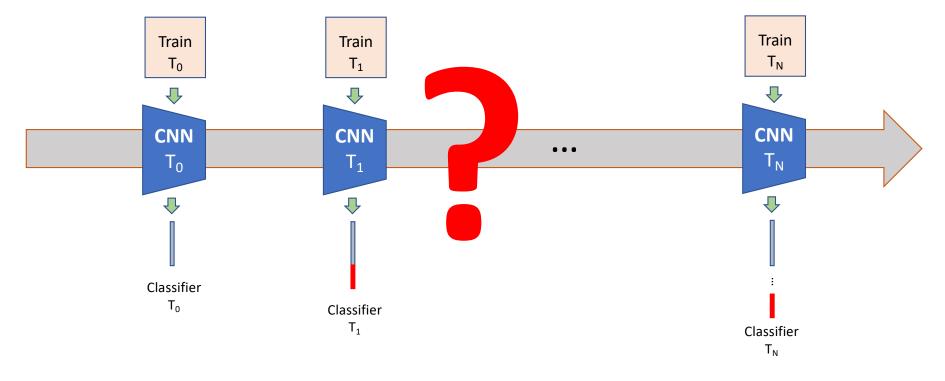


## Problem continues



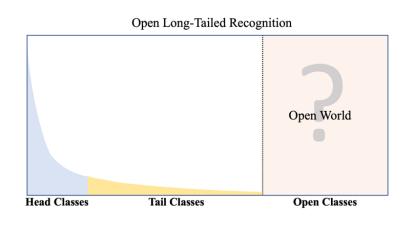
## Deep learning system

## Problem continues



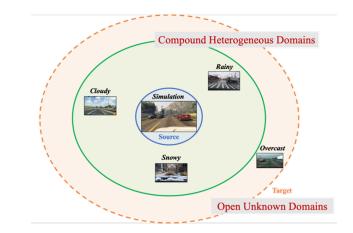
## Realistic machine learning system

## Thank you!





OLTR





OCDA