# Vanishing Gradients in Reinforcement Finetuning of Language Models

## **Noam Razin**

Joint work with Hattie Zhou, Omid Saremi, Vimal Thilak, Arwen Bradley, Preetum Nakkiran, Joshua Susskind, Etai Littwin

DLCT 9 February 2024

Ú

**LM –** Neural network trained on large amounts of (internet) text data to produce a **distribution over text** 



**LM –** Neural network trained on large amounts of (internet) text data to produce a **distribution over text** 



**LM –** Neural network trained on large amounts of (internet) text data to produce a **distribution over text** 



LMs are typically **autoregressive**:  $p_{\theta}(\mathbf{y}|\mathbf{x}) = \prod_{l=1}^{L} p_{\theta}(\mathbf{y}_{l}|\mathbf{x}, \mathbf{y}_{\leq l-1})$ 

**LM –** Neural network trained on large amounts of (internet) text data to produce a **distribution over text** 



LMs are typically **autoregressive**:  $p_{\theta}(\mathbf{y}|\mathbf{x}) = \prod_{l=1}^{L} p_{\theta}(y_l|\mathbf{x}, \mathbf{y}_{\leq l-1})$ 

**softmax** is used for producing next-token probabilities

LMs are adapted to human preferences and downstream tasks via **finetuning** 

LMs are adapted to human preferences and downstream tasks via **finetuning** 

#### **Supervised Finetuning (SFT)**

Minimize cross entropy loss over labeled inputs via gradient-based methods



LMs are adapted to human preferences and downstream tasks via **finetuning** 

#### **Supervised Finetuning (SFT)**

Minimize cross entropy loss over labeled inputs via gradient-based methods



outputs sampled from conditional distribution  $\,\mathcal{D}(\cdot|\mathbf{x})$ 

LMs are adapted to human preferences and downstream tasks via **finetuning** 

#### **Supervised Finetuning (SFT)**

Minimize cross entropy loss over labeled inputs via gradient-based methods



outputs sampled from conditional distribution  $\,\mathcal{D}(\cdot|\mathbf{x})$ 

Expected loss for input **x**:  $\mathcal{L}_{\theta}(\mathbf{x}) = \mathbb{E}_{\mathbf{y} \sim \mathcal{D}(\cdot | \mathbf{x})} \left[ -\ln p_{\theta}(\mathbf{y} | \mathbf{x}) \right]$ 

LMs are adapted to human preferences and downstream tasks via **finetuning** 

#### **Supervised Finetuning (SFT)**

Minimize cross entropy loss over labeled inputs via gradient-based methods



outputs sampled from conditional distribution  $\,\mathcal{D}(\cdot|\mathbf{x})$ 

Expected loss for input **x**:  $\mathcal{L}_{\theta}(\mathbf{x}) = \mathbb{E}_{\mathbf{y} \sim \mathcal{D}(\cdot | \mathbf{x})} \left[ -\ln p_{\theta}(\mathbf{y} | \mathbf{x}) \right]$ 

#### Limitations:

LMs are adapted to human preferences and downstream tasks via **finetuning** 

#### Supervised Finetuning (SFT)

Minimize cross entropy loss over labeled inputs via gradient-based methods



outputs sampled from conditional distribution  $\mathcal{D}(\cdot|\mathbf{x})$ 

Expected loss for input x:  $\mathcal{L}_{\theta}(\mathbf{x}) = \mathbb{E}_{\mathbf{v} \sim \mathcal{D}(\cdot | \mathbf{x})} \left[ -\ln p_{\theta}(\mathbf{y} | \mathbf{x}) \right]$ 

#### Limitations:



Hard to formalize human preferences through labels

LMs are adapted to human preferences and downstream tasks via **finetuning** 

#### Supervised Finetuning (SFT)

Minimize cross entropy loss over labeled inputs via gradient-based methods



outputs sampled from conditional distribution  $\mathcal{D}(\cdot|\mathbf{x})$ 

Expected loss for input x:  $\mathcal{L}_{\theta}(\mathbf{x}) = \mathbb{E}_{\mathbf{v} \sim \mathcal{D}(\cdot | \mathbf{x})} \left[ -\ln p_{\theta}(\mathbf{y} | \mathbf{x}) \right]$ 

#### Limitations:



Hard to formalize human preferences through labels

**(5))** Labeled data is expensive

#### Limitations of SFT led to wide adoption of a **reinforcement learning**-based approach

(e.g. Ziegler et al. 2019, Stiennon et al. 2020, Ouyang et al. 2022, Bai et al. 2022, Dubois et al. 2023, Touvron et al. 2023)

## Limitations of SFT led to wide adoption of a **reinforcement learning**-based approach

(e.g. Ziegler et al. 2019, Stiennon et al. 2020, Ouyang et al. 2022, Bai et al. 2022, Dubois et al. 2023, Touvron et al. 2023)

## **Reinforcement Finetuning (RFT)**

Maximize reward over unlabeled inputs via **policy gradient algorithms** 



## Limitations of SFT led to wide adoption of a **reinforcement learning**-based approach

(e.g. Ziegler et al. 2019, Stiennon et al. 2020, Ouyang et al. 2022, Bai et al. 2022, Dubois et al. 2023, Touvron et al. 2023)

#### **Reinforcement Finetuning (RFT)**

Maximize reward over unlabeled inputs via **policy gradient algorithms** 

**equal to a set of the set of th** 

Expected reward for input x:  $V_{\theta}(\mathbf{x}) = \mathbb{E}_{\mathbf{y} \sim p_{\theta}(\cdot | \mathbf{x})} [r(\mathbf{x}, \mathbf{y})]$ 

## Limitations of SFT led to wide adoption of a **reinforcement learning**-based approach

(e.g. Ziegler et al. 2019, Stiennon et al. 2020, Ouyang et al. 2022, Bai et al. 2022, Dubois et al. 2023, Touvron et al. 2023)

#### **Reinforcement Finetuning (RFT)**

Maximize reward over unlabeled inputs via **policy gradient algorithms** 

**Figure**, **•••**, **Figure**, **reward** function  $r(\mathbf{x}, \mathbf{y})$ 

Expected reward for input x:  $V_{\theta}(\mathbf{x}) = \mathbb{E}_{\mathbf{y} \sim p_{\theta}(\cdot | \mathbf{x})} [r(\mathbf{x}, \mathbf{y})]$ 

#### Reward function $r(\mathbf{x}, \mathbf{y})$ can be:

## Limitations of SFT led to wide adoption of a **reinforcement learning**-based approach

(e.g. Ziegler et al. 2019, Stiennon et al. 2020, Ouyang et al. 2022, Bai et al. 2022, Dubois et al. 2023, Touvron et al. 2023)

## **Reinforcement Finetuning (RFT)**

Maximize reward over unlabeled inputs via **policy gradient algorithms** 

**Figure**, **•••**, **Figure** reward function  $r(\mathbf{x}, \mathbf{y})$ 

Expected reward for input x:  $V_{\theta}(\mathbf{x}) = \mathbb{E}_{\mathbf{y} \sim p_{\theta}(\cdot | \mathbf{x})} [r(\mathbf{x}, \mathbf{y})]$ 

#### Reward function $r(\mathbf{x}, \mathbf{y})$ can be:



## Limitations of SFT led to wide adoption of a **reinforcement learning**-based approach

(e.g. Ziegler et al. 2019, Stiennon et al. 2020, Ouyang et al. 2022, Bai et al. 2022, Dubois et al. 2023, Touvron et al. 2023)

## **Reinforcement Finetuning (RFT)**

Maximize reward over unlabeled inputs via **policy gradient algorithms** 

reward function  $r(\mathbf{x}, \mathbf{y})$ 

Expected reward for input x:  $V_{\theta}(\mathbf{x}) = \mathbb{E}_{\mathbf{v} \sim p_{\theta}(\cdot | \mathbf{x})} [r(\mathbf{x}, \mathbf{y})]$ 

#### Reward function $r(\mathbf{x}, \mathbf{y})$ can be:



Learned from human preferences



Fundamental vanishing gradients problem in RFT

 $abla_{ heta} \mathbf{V}_{ heta}(\mathbf{x}) pprox \mathbf{0}$ 

Fundamental vanishing gradients problem in RFT

 $abla_{ heta} \mathbf{V}_{ heta}(\mathbf{x}) pprox \mathbf{0}$ 

Vanishing gradients are prevalent and harm ability to maximize reward



Fundamental vanishing gradients problem in RFT

Vanishing gradients are prevalent and harm ability to maximize reward



 $\nabla_{\theta} \mathbf{V}_{\theta}(\mathbf{x}) \approx \mathbf{0}$ 

Exploring ways to overcome vanishing gradients in RFT



Fundamental vanishing gradients problem in RFT

Vanishing gradients are prevalent and harm ability to maximize reward



 $\nabla_{\theta} \mathbf{V}_{\theta}(\mathbf{x}) \approx \mathbf{0}$ 

Exploring ways to overcome vanishing gradients in RFT



5/18

 $STD_{\mathbf{y} \sim p_{\theta}(\cdot | \mathbf{x})}[r(\mathbf{x}, \mathbf{y})]$  – reward std of  $\mathbf{x}$  under the model

 $STD_{\mathbf{y} \sim p_{\theta}(\cdot | \mathbf{x})}[r(\mathbf{x}, \mathbf{y})]$  – reward std of  $\mathbf{x}$  under the model

#### Theorem

$$\|\nabla_{\theta} V_{\theta}(\mathbf{x})\| = O\left(\mathrm{STD}_{\mathbf{y} \sim p_{\theta}(\cdot | \mathbf{x})} [r(\mathbf{x}, \mathbf{y})]^{2/3}\right)$$

\*Same holds for PPO gradient

 $STD_{\mathbf{y} \sim p_{\theta}(\cdot | \mathbf{x})}[r(\mathbf{x}, \mathbf{y})]$  – reward std of  $\mathbf{x}$  under the model

#### Theorem

$$\|\nabla_{\theta} V_{\theta}(\mathbf{x})\| = O\left(\mathrm{STD}_{\mathbf{y} \sim p_{\theta}(\cdot | \mathbf{x})} [r(\mathbf{x}, \mathbf{y})]^{2/3}\right)$$

\*Same holds for PPO gradient

 Expected gradient for an input vanishes when reward std is small, even if reward mean is suboptimal

 $STD_{\mathbf{y} \sim p_{\theta}(\cdot | \mathbf{x})}[r(\mathbf{x}, \mathbf{y})]$  – reward std of  $\mathbf{x}$  under the model

#### Theorem

$$\|\nabla_{\theta} V_{\theta}(\mathbf{x})\| = O\left(\mathrm{STD}_{\mathbf{y} \sim p_{\theta}(\cdot | \mathbf{x})} [r(\mathbf{x}, \mathbf{y})]^{2/3}\right)$$

\*Same holds for PPO gradient

 Expected gradient for an input vanishes when reward std is small, even if reward mean is suboptimal

**Proof Idea:** Stems from use of softmax + reward maximization objective

 $STD_{\mathbf{y} \sim p_{\theta}(\cdot | \mathbf{x})}[r(\mathbf{x}, \mathbf{y})]$  – reward std of  $\mathbf{x}$  under the model

#### Theorem

$$\|\nabla_{\theta} V_{\theta}(\mathbf{x})\| = O\left(\mathrm{STD}_{\mathbf{y} \sim p_{\theta}(\cdot | \mathbf{x})} [r(\mathbf{x}, \mathbf{y})]^{2/3}\right)$$

\*Same holds for PPO gradient

 Expected gradient for an input vanishes when reward std is small, even if reward mean is suboptimal

**Proof Idea:** Stems from use of softmax + reward maximization objective

Note: Bound applies to expected gradients of individual inputs (as opposed to of batch/population)

 $STD_{\mathbf{y} \sim p_{\theta}(\cdot | \mathbf{x})}[r(\mathbf{x}, \mathbf{y})]$  – reward std of  $\mathbf{x}$  under the model

#### Theorem

$$\|\nabla_{\theta} V_{\theta}(\mathbf{x})\| = O\left(\mathrm{STD}_{\mathbf{y} \sim p_{\theta}(\cdot | \mathbf{x})} [r(\mathbf{x}, \mathbf{y})]^{2/3}\right)$$

\*Same holds for PPO gradient

 Expected gradient for an input vanishes when reward std is small, even if reward mean is suboptimal

**Proof Idea:** Stems from use of softmax + reward maximization objective

Note: Bound applies to expected gradients of individual inputs (as opposed to of batch/population)

Can be problematic when finetuning text distribution differs from pretraining

Fundamental vanishing gradients problem in RFT

Vanishing gradients are prevalent and harm ability to maximize reward



 $\nabla_{\theta} \mathbf{V}_{\theta}(\mathbf{x}) \approx \mathbf{0}$ 

Exploring ways to overcome vanishing gradients in RFT



Fundamental vanishing gradients problem in RFT

Vanishing gradients are prevalent and harm ability to maximize reward



 $\nabla_{\theta} \mathbf{V}_{\theta}(\mathbf{x}) \approx \mathbf{0}$ 

Exploring ways to overcome vanishing gradients in RFT



<u>Benchmark</u>: GRUE (Ramamurthy et al. 2023) 7 language generation datasets

<u>Benchmark</u>: GRUE (Ramamurthy et al. 2023) <u>Mc</u> 7 language generation datasets

Models: GPT-2 and T5-base

<u>Benchmark</u>: GRUE (Ramamurthy et al. 2023) <u>Models</u>: GPT-2 and T5-base 7 language generation datasets

#### **Finding I**

3 of 7 datasets contain considerable # of train inputs with small reward std and low reward
<u>Benchmark</u>: GRUE (Ramamurthy et al. 2023) <u>Models</u>: GPT-2 and T5-base 7 language generation datasets



<u>Benchmark</u>: GRUE (Ramamurthy et al. 2023) <u>Models</u>: GPT-2 and T5-base 7 language generation datasets

Finding I

vanishing gradients

3 of 7 datasets contain considerable # of train inputs with small reward std and low reward

NarrativeQA (many inputs w/ small std)



<u>Benchmark</u>: GRUE (Ramamurthy et al. 2023) <u>Models</u>: GPT-2 and T5-base 7 language generation datasets

 Finding I

 3 of 7 datasets contain considerable # of train inputs with small reward std and low reward

NarrativeQA (many inputs w/ small std)

IMDB (few inputs w/ small std)



As expected: Text distribution substantially differs from pretraining distribution

As expected: Text distribution substantially differs from pretraining distribution considerable amount of inputs with small reward std

As expected: Text distribution substantially differs from pretraining distribution

considerable amount of inputs with small reward std

vanishing gradients

As expected: Text distribution substantially differs from pretraining distribution

considerable amount of inputs with small reward std

vanishing gradients



# 8/18 Which Datasets Suffer From Vanishing Gradients in RFT? As expected: Text distribution substantially differs from pretraining distribution considerable amount of inputs with small reward std vanishing gradients Few inputs with small Many inputs with small reward std and low reward reward std and low reward NarrativeQA IMDB



<u>Benchmark</u>: GRUE (Ramamurthy et al. 2023) <u>Mo</u> 7 language generation datasets

Models: GPT-2 and T5-base

<u>Benchmark</u>: GRUE (Ramamurthy et al. 2023) <u>Models</u>: GPT-2 and T5-base 7 language generation datasets

#### **Finding II**

As expected, RFT has limited impact on the reward of inputs with small reward std

<u>Benchmark</u>: GRUE (Ramamurthy et al. 2023) <u>Models</u>: GPT-2 and T5-base 7 language generation datasets

#### **Finding II**

As expected, RFT has limited impact on the reward of inputs with small reward std



<u>Benchmark</u>: GRUE (Ramamurthy et al. 2023) <u>Models</u>: GPT-2 and T5-base 7 language generation datasets

#### **Finding II**

As expected, RFT has limited impact on the reward of inputs with small reward std



9/18

<u>Benchmark</u>: GRUE (Ramamurthy et al. 2023) <u>Models</u>: GPT-2 and T5-base 7 language generation datasets

#### **Finding II**

As expected, RFT has limited impact on the reward of inputs with small reward std



9/18

<u>Benchmark</u>: GRUE (Ramamurthy et al. 2023) <u>Mc</u> 7 language generation datasets

Models: GPT-2 and T5-base

<u>Benchmark</u>: GRUE (Ramamurthy et al. 2023) <u>Models</u>: GPT-2 and T5-base 7 language generation datasets

#### **Finding III**

RFT performance is worse when inputs with small reward std are prevalent

<u>Benchmark</u>: GRUE (Ramamurthy et al. 2023) <u>Models</u>: GPT-2 and T5-base 7 language generation datasets

#### **Finding III**

RFT performance is worse when inputs with small reward std are prevalent



#### 11/18

# Vanishing Gradients or Insufficient Exploration?

We saw that vanishing expected gradients is indicative of RFT performance

We saw that vanishing expected gradients is indicative of RFT performance

measured by reward std

We saw that vanishing expected gradients is indicative of RFT performance

measured by reward std

#### **Possible Confounding Factor: Insufficient Exploration**

We saw that vanishing expected gradients is indicative of RFT performance

measured by reward std

#### **Possible Confounding Factor: Insufficient Exploration**

Large output space in language generation

We saw that vanishing expected gradients is indicative of RFT performance

measured by reward std

#### **Possible Confounding Factor: Insufficient Exploration**

Large output space in language generation — challenge of exploration

(e.g. Ranzato et al. 2016, Choshen et al. 2020)

We saw that vanishing expected gradients is indicative of RFT performance

measured by reward std

#### **Possible Confounding Factor: Insufficient Exploration**

Large output space in language generation — challenge of exploration

(e.g. Ranzato et al. 2016, Choshen et al. 2020)

 $\implies$  challenge of accurately estimating  $\nabla_{\theta} V_{\theta}(\mathbf{x})$ 

We saw that vanishing expected gradients is indicative of RFT performance

measured by reward std

#### **Possible Confounding Factor: Insufficient Exploration**

Large output space in language generation  $\longrightarrow$  challenge of exploration

(e.g. Ranzato et al. 2016, Choshen et al. 2020)

 $\implies$  challenge of accurately estimating  $\nabla_{\theta} V_{\theta}(\mathbf{x})$ 

**Q:** Does the difficulty of RFT to maximize reward stem from vanishing gradients or just insufficient exploration?

We saw that vanishing expected gradients is indicative of RFT performance

measured by reward std

#### **Possible Confounding Factor: Insufficient Exploration**

Large output space in language generation — challenge of exploration

(e.g. Ranzato et al. 2016, Choshen et al. 2020)

 $\implies$  challenge of accurately estimating  $\nabla_{\theta} V_{\theta}(\mathbf{x})$ 

**Q**: Does the difficulty of RFT to maximize reward stem from vanishing gradients or just insufficient exploration?

**O We address Q via controlled experiments and theoretical analysis** 

#### **Controlled Experiments**

Environments with **perfect exploration**, i.e. RFT has access to expected gradients

#### **Controlled Experiments**

# Environments with **perfect exploration**, i.e. RFT has access to expected gradients



#### **Controlled Experiments**

Environments with **perfect exploration**, i.e. RFT has access to expected gradients



#### **Theoretical Analysis**

Simplified setting of linear classification over orthonormal data with **perfect exploration** 

#### **Controlled Experiments**

# Environments with **perfect exploration**, i.e. RFT has access to expected gradients



#### **Theoretical Analysis**

Simplified setting of linear classification over orthonormal data with **perfect exploration** 

#### Theorem

Time it takes to correctly classify input  $\mathbf{x}$  is: in RFT -  $\Omega(1/\text{STD}_{\mathbf{y} \sim p_{\theta}(0)}(\cdot | \mathbf{x}) [r(\mathbf{x}, \mathbf{y})]^2)$ in SFT -  $O(\ln(1/\text{STD}_{\mathbf{y} \sim p_{\theta}(0)}(\cdot | \mathbf{x}) [r(\mathbf{x}, \mathbf{y})]))$ 

#### **Controlled Experiments**

# Environments with **perfect exploration**, i.e. RFT has access to expected gradients



#### **Theoretical Analysis**

Simplified setting of linear classification over orthonormal data with **perfect exploration** 

#### Theorem

Time it takes to correctly classify input  $\mathbf{x}$  is: in RFT -  $\Omega(1/\text{STD}_{\mathbf{y} \sim p_{\theta}(0)}(\cdot | \mathbf{x}) [r(\mathbf{x}, \mathbf{y})]^2)$ in SFT -  $O(\ln(1/\text{STD}_{\mathbf{y} \sim p_{\theta}(0)}(\cdot | \mathbf{x}) [r(\mathbf{x}, \mathbf{y})]))$ 

 RFT struggles to maximize reward for inputs with small reward std despite perfect exploration

# Main Contributions: Vanishing Gradients in RFT

Fundamental vanishing gradients problem in RFT

Vanishing gradients are prevalent and harm ability to maximize reward



 $\nabla_{\theta} \mathbf{V}_{\theta}(\mathbf{x}) \approx \mathbf{0}$ 

Exploring ways to overcome vanishing gradients in RFT



# Main Contributions: Vanishing Gradients in RFT

Fundamental vanishing gradients problem in RFT

Vanishing gradients are prevalent and harm ability to maximize reward



 $\nabla_{\theta} \mathbf{V}_{\theta}(\mathbf{x}) \approx \mathbf{0}$ 

Exploring ways to overcome vanishing gradients in RFT



## **Inadequacy of Common Heuristics**

Vanishing gradients in RFT are resilient to common heuristics:

## **Inadequacy of Common Heuristics**

Vanishing gradients in RFT are resilient to common heuristics:

• Increasing learning rate
Vanishing gradients in RFT are resilient to common heuristics:

- Increasing learning rate
- Adding temperature to logits

Vanishing gradients in RFT are resilient to common heuristics:

- Increasing learning rate
- Adding temperature to logits
- Entropy regularization

Vanishing gradients in RFT are resilient to common heuristics:

- Increasing learning rate
- Adding temperature to logits
- Entropy regularization

Expected to help?

Vanishing gradients in RFT are resilient to common heuristics:

- Increasing learning rate
- Adding temperature to logits
- Entropy regularization



Vanishing gradients in RFT are resilient to common heuristics:

- Increasing learning rate
- Adding temperature to logits
- Entropy regularization



**Results:** As expected, no improvement to the reward of RFT

#### Dataset: NarrativeQA

	Train Reward	Test Reward
RFT <sup>*</sup> SFT + RFT	$\begin{array}{r} 0.101 \pm 0.009 \\ 0.537 \pm 0.005 \end{array}$	$\begin{array}{c} 0.116 \pm 0.000 \\ 0.544 \pm 0.003 \end{array}$
RFT with learning rate $2 \cdot 10^{-5}$ RFT with learning rate $2 \cdot 10^{-4}$ RFT with learning rate $2 \cdot 10^{-3}$	$\begin{array}{r} 0.012 \pm 0.010 \\ 0.053 \pm 0.010 \\ 0.039 \pm 0.018 \end{array}$	$\begin{array}{c} 0.020\pm0.017\ 0.048\pm0.016\ 0.012\pm0.020 \end{array}$
RFT with temperature 1.5 RFT with temperature 2 RFT with temperature 2.5	$\begin{array}{r} 0.077  \pm  0.021 \\ 0.060  \pm  0.018 \\ 0.044  \pm  0.004 \end{array}$	$\begin{array}{r} 0.118  \pm  0.002 \\ 0.104  \pm  0.009 \\ 0.088  \pm  0.009 \end{array}$
RFT with entropy regularization 0.01 RFT with entropy regularization 0.1 RFT with entropy regularization 1	$\begin{array}{c} 0.080 \pm 0.006 \\ 0.024 \pm 0.005 \\ 0.011 \pm 0.000 \end{array}$	$\begin{array}{c} 0.113  \pm  0.002 \\ 0.019  \pm  0.007 \\ 0.013  \pm  0.010 \end{array}$

<sup>\*</sup>With default hyperparameters: learning rate  $2 \cdot 10^{-6}$ , temperature 1, entropy regularization 0

Common practice is to perform initial SFT phase before RFT (e.g. Ouyang et al. 2022)

Common practice is to perform initial SFT phase before RFT (e.g. Ouyang et al. 2022)

**Observation –** Initial SFT phase reduces number of inputs with small reward std

Common practice is to perform initial SFT phase before RFT (e.g. Ouyang et al. 2022)

**Observation –** Initial SFT phase reduces number of inputs with small reward std



Common practice is to perform initial SFT phase before RFT (e.g. Ouyang et al. 2022)

**Observation –** Initial SFT phase reduces number of inputs with small reward std



**①** Importance of SFT in RFT pipeline: mitigates vanishing gradients

Limitation of initial SFT phase – Requires labeled data (S))

Limitation of initial SFT phase – Requires labeled data (S))

**Expectation –** If SFT phase is beneficial due to mitigating vanishing gradients for RFT

Limitation of initial SFT phase – Requires labeled data (S))

**Expectation –** If SFT phase is beneficial due to mitigating vanishing gradients for RFT

A few steps of SFT on small # of labeled samples should suffice

Limitation of initial SFT phase – Requires labeled data (S))

**Expectation –** If SFT phase is beneficial due to mitigating vanishing gradients for RFT

A few steps of SFT on small # of labeled samples should suffice

	RFT After Partial SFT Reward						
	م RFT After Full SFT Reward						
•	Step 100	0.96	1.01	1.01	1.01	1.02	1.00
•	tion 80	0.95	1.00	1.00	0.99	0.99	1.01
1	niza 60	0.96	0.99	0.99	0.98	0.98	0.99
	Dptir 40	0.96	0.96	0.96	0.95	0.96	0.96
	5FT ( 20	0.90	0.86	0.91	0.86	0.91	0.90
	of 5	0.60	0.63	0.62	0.60	0.59	0.63
	%	1	20	40 % of SFT	60 Samples	80	100

NarrativeQA (train)

Limitation of initial SFT phase – Requires labeled data (S))

**Expectation –** If SFT phase is beneficial due to mitigating vanishing gradients for RFT

A few steps of SFT on small # of labeled samples should suffice

	RFT After Partial SFT Reward RFT After Full SFT Reward						
,	Steps 100	0.96	1.01	1.01	1.01	1.02	1.00
	- 80 80	0.95	1.00	1.00	0.99	0.99	1.01
I	nizat 60	0.96	0.99	0.99	0.98	0.98	0.99
	)ptin 40	0.96	0.96	0.96	0.95	0.96	0.96
	5FT ( 20	0.90	0.86	0.91	0.86	0.91	0.90
	of 5	0.60	0.63	0.62	0.60	0.59	0.63
	%	1	20	40 % of SFT	<sup>60</sup> Samples	80	100

NarrativeQA (train)

Limitation of initial SFT phase – Requires labeled data (S))

**Expectation –** If SFT phase is beneficial due to mitigating vanishing gradients for RFT

A few steps of SFT on small # of labeled samples should suffice

	10		RFT After Partial SFT Reward RFT After Full SFT Reward				
in)	Steps 100	0.96	1.01	1.01	1.01	1.02	1.00
QA (trai	tion -	0.95	1.00	1.00	0.99	0.99	1.01
	nizat 60	0.96	0.99	0.99	0.98	0.98	0.99
tive	Dptin 40	0.96	0.96	0.96	0.95	0.96	0.96
ırrat	5FT (	0.90	0.86	0.91	0.86	0.91	0.90
Za	of 5	0.60	0.63	0.62	0.60	0.59	0.63
	%	1	20	40 % of SFT	60 Samples	80	100

 The initial SFT phase does not need to be expensive!

# $abla_{ heta} \mathbf{V}_{ heta}(\mathbf{x}) pprox \mathbf{0}$

#### Expected gradient for an input vanishes in RFT

if the input's reward std is small

 $abla_{ heta} \mathbf{V}_{ heta}(\mathbf{x}) pprox \mathbf{0}$ 

**Expected gradient for an input vanishes in RFT** if the input's reward std is small



Experiments + theory: vanishing gradients in RFT are prevalent and detrimental to maximizing reward

 $abla_{\theta} \mathbf{V}_{\theta}(\mathbf{x}) \approx \mathbf{0}$ Expected gradient for an input vanishes in RFT if the input's reward std is small



Experiments + theory: vanishing gradients in RFT are prevalent and detrimental to maximizing reward



**Initial SFT phase** allows overcoming vanishing gradients in RFT, and **does not need to be expensive** 

 $abla_{\theta} \mathbf{V}_{\theta}(\mathbf{x}) \approx \mathbf{0}$ Expected gradient for an input vanishes in RFT if the input's reward std is small

Experiments + theory: vanishing gradients in RFT are prevalent and detrimental to maximizing reward

**Initial SFT phase** allows overcoming vanishing gradients in RFT, and **does not need to be expensive** 

**Or Reward std is a key quantity to track for successful RFT** 

#### Expected gradient for an input vanishes in RFT

if the input's reward std is small



 $abla_{ heta} \mathbf{V}_{ heta}(\mathbf{x}) pprox \mathbf{0}$ 

Experiments + theory: vanishing gradients in RFT are prevalent and detrimental to maximizing reward



**Initial SFT phase** allows overcoming vanishing gradients in RFT, and **does not need to be expensive** 

**Or Reward std is a key quantity to track for successful RFT** 

Thank You!