

Understanding and Mitigating the Pre-training Noise on Downstream Tasks

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<https://arxiv.org/pdf/2309.17002.pdf>

<https://arxiv.org/abs/2403.06869.pdf>



Content

- Background and Motivation of Noisy Model Learning
- Motivating Experiments on Effects of Pre-training Noise
- Feature Space Analysis of Pre-training Noise
- Mitigation of Pre-training Noise on Downstream Tasks
- More Experiments and Discussions

Background and Motivation

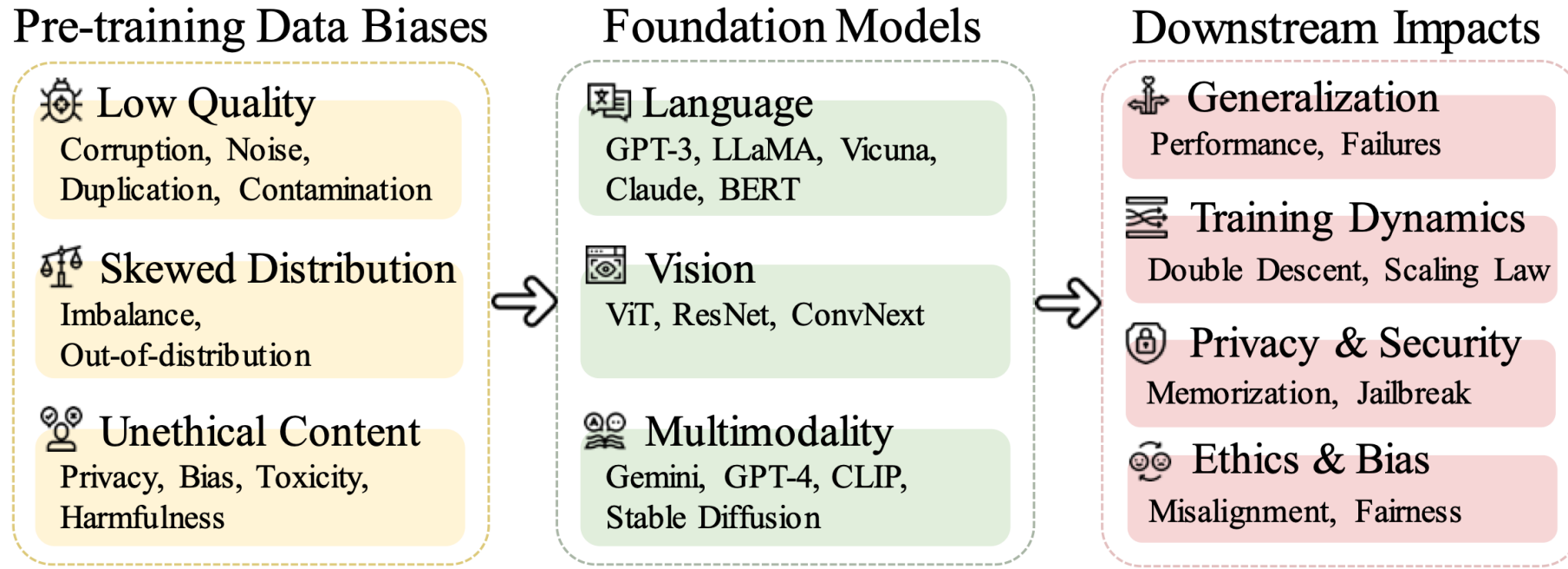
Catastrophic Inheritance of Large Foundation Models

Noisy Model Learning

Background – Large Foundation Models

- Large foundation models require **massive** pre-training data
 - Open CLIP – **2.0 billion** image-text pairs
 - Llama – **2.0T** tokens
- Adaption of foundation models
 - **Pre-training** on proxy tasks
 - **Tuning** on specific downstream tasks (linear probing, parameter efficient tuning, full fine-tuning, etc.)
- Success of foundation models attributed to the pre-training data
 - Large-scale pre-training data are usually collected from web
 - **Inevitable noise (and other types of bias) in pre-training data that may lead to unexpected generalization performance and behavior**

Pre-training Bias -> Catastrophic Inheritance



- Pre-training **biases** used to train **foundation models** may be **inherited** to downstream tasks with **malicious impacts**
- Unexplored direction yet very important and interesting

Examples of Catastrophic Inheritance

Table 1: Realistic examples of catastrophic inheritance from published papers or news.

Example	Domain	Source
Stable Diffusion models was trained on Laion-5B, which contains hundreds of harmful images of child sexual abuse material (CSAM). Then, the model was reported to memorize during training and generate CSAM at production.	Ethics and privacy	[Birhane et al., 2023, Forbes, 2023, Thiel, 2023]
At least 50% of poisoning, adversarial, and backdoor vulnerabilities will be inherited from pre-training data to fine-tuned models, which can be easily triggered at the deployment. Jailbreaks may also relate to pre-training biases.	Security	[Wang et al., 2018, Zhang et al., 2022, Carlini et al., 2023a, Zou et al., 2023]
An MIT student asked AI to make her headshot more ‘professional.’ It gave her lighter skin and blue eyes. Country bias also found in language models.	Bias	[Boston.com, 2023, Wang et al., 2023a]
Fine-tuning LLMs on only 10 adversarially designed or even benign samples leads to degradation of safety alignment, which costs less than \$0.2 using API.	Misalignment	[Qi et al., 2023]
Noisy labels contained in pre-trained data always hurt downstream OOD performance; more than 10% noisy data will hurt in-domain performance.	Generalization	[Chen et al., 2024]
Large language models like GPT-3.5 exhibited an accuracy reduction of 18.12% when answering non-English medical questions. Similar for coding tasks.	Model behaviors	[Jin et al., 2024, Zheng et al.]
Noise in the pre-training data strengthen the double descent phenomena, where the critical point of LLMs overfitting/memorizing data appears earlier.	Training dynamics	[Nakkiran et al., 2019]

This work

This Work: Inevitable Pre-training Noise

- Evidence in CLIP
 - OpenAI trains CLIP on **WIT-400M** (not public)
 - OpenCLIP trains CLIP on **Laion-2B**, with more noisy image-text pairs
 - Yet they achieve **similar zero-shot performance**

	Data	Arch.	ImageNet	VTAB+
CLIP [55]	WIT-400M	L/14	75.5	55.8
Ours	LAION-2B	L/14	75.2	54.6
Ours	LAION-2B	H/14	<u>78.0</u>	<u>56.4</u>

Noisy Model Learning

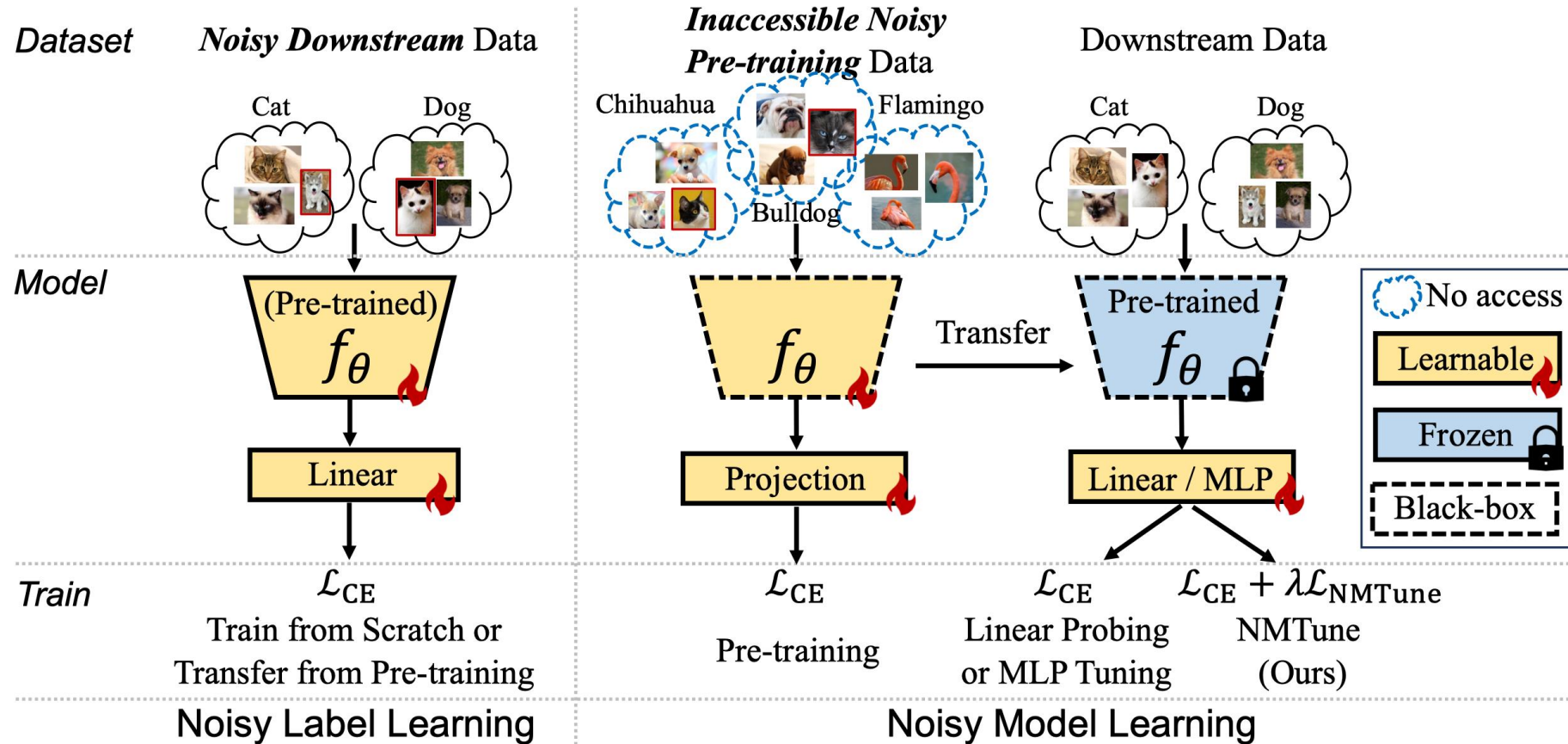
- Noisy Label Learning
 - Data of **downstream task** contain noise
 - Noise hurts downstream performance
 - Improve the model performance when downstream contains noise
 - Many techniques, widely studied
- Noisy Model Learning (of foundation models)
 - Data of **pre-training task** contain noise
 - Data of downstream tasks are clean (or noisy)
 - Does the pre-training noise affect the downstream generalization? If so, how?
 - **Unexplored** before, perhaps intuitively believe the cleaner, the better

Motivation on Noisy Model Learning

Noisy Model Learning (of foundation models)

- How does the **noise** in pre-training data **affect** the performance of pre-trained models on downstream tasks?
- How can we **mitigate** the detrimental effect of pre-training noise on downstream, if any?
- Possible black-box and noisy pre-training data
 - Massive size, expired urls...
- Possible (partially) black-box pre-trained models
 - Private models
 - Expensive computational requirement of full fine-tuning

Noisy Model vs. Noisy Label



Understanding the Effects of Pre-training Noise

Empirical Study

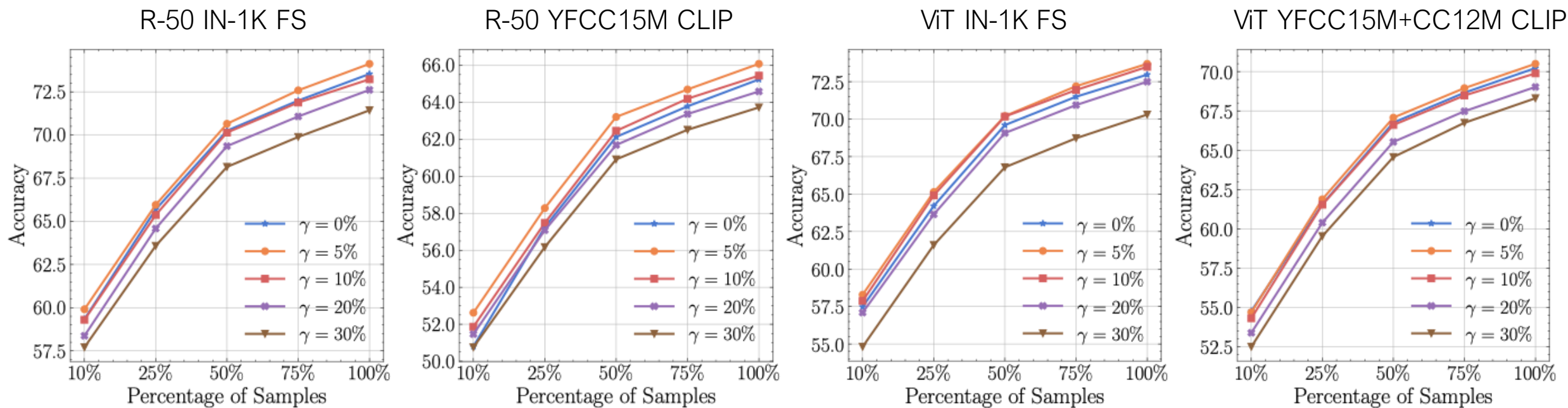
Effect of Pre-training Noise on Downstream

- Two pre-training paradigms/dataset
 - YFCC15M (and CC12M) – Image-Text Pair Contrastive Learning (CLIP)
 - ImageNet1K – Fully-Supervised Learning (FS)
- Introduce noise into the datasets
 - YFCC15M (and CC12M) – randomly swap the image-text pairs
 - ImageNet1K – randomly swap the label
- Two models pre-trained of different scales: ResNet-50 and ViT-B-16
 - for CLIP, ViT-B-16 is trained on YFCC15M+CC12M, and ResNet-50 on YFCC15M
 - for FS, both are trained on ImageNet-1K
- Train models with noise ratios {0, 5, 10, 20, 30}%
 - Heavy regularizations are adopted during pre-training

Downstream Classification Generalization

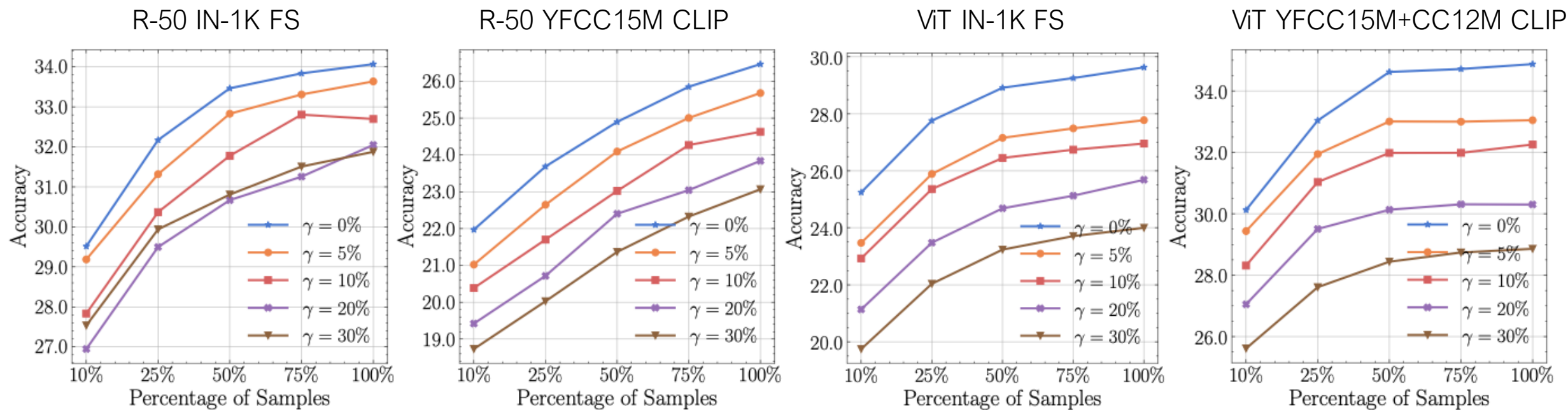
- **In-Domain (ID) Evaluation**
 - 14 vision datasets, including CIFAR-100, Flowers102, Food101, RESISC45, DTD, etc.
 - The training set and the testing set are of the **same distribution**
- **Out-of-Domain (OOD) Evaluation**
 - DomainNet: Clipart, Real, Sketch, Inpainting
 - ImageNet-Variants: IN-v2, IN-R, IN-Sketch, IN-A, IN-Vid, ObjectNet
 - The training set and the testing sets are of **different distribution**
- Report **average performance** over all datasets with various tuning
 - Linear probing, LoRA (of ViT-B-16), full fine-tuning

ID Linear Probing Evaluation



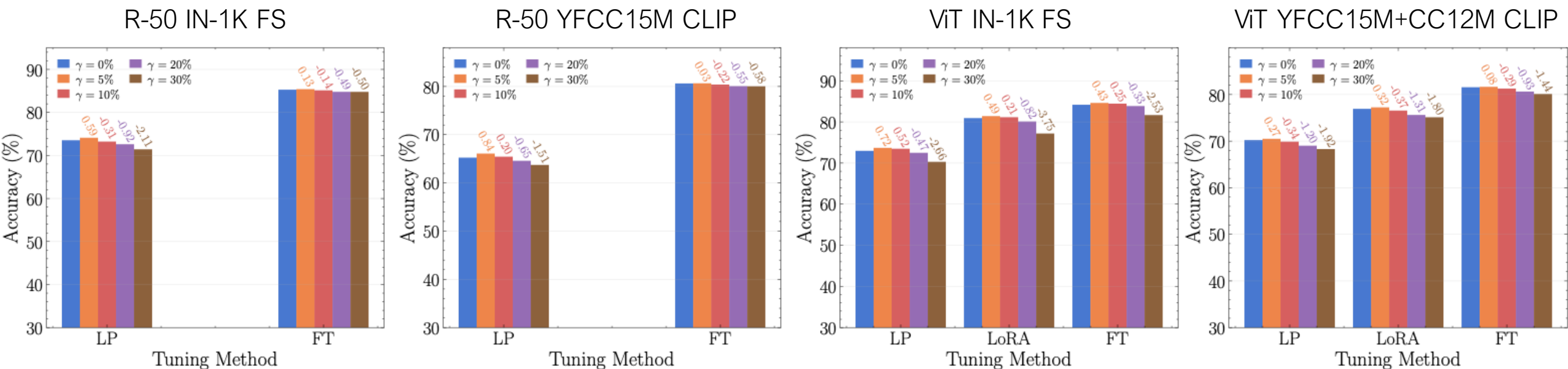
- Slight pre-training noise (5% or 10%) benefits ID classification tasks
- Further increase noise in pre-training hurts downstream performance

OOD Linear Probing Evaluation



- Pre-training noise always deteriorates OOD tasks
- As noise ratio increases, the performance consistently decreases

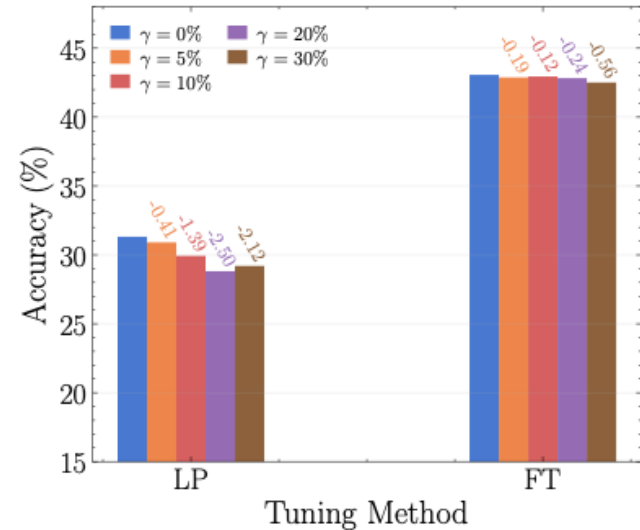
ID Eval. with Different Tuning Methods



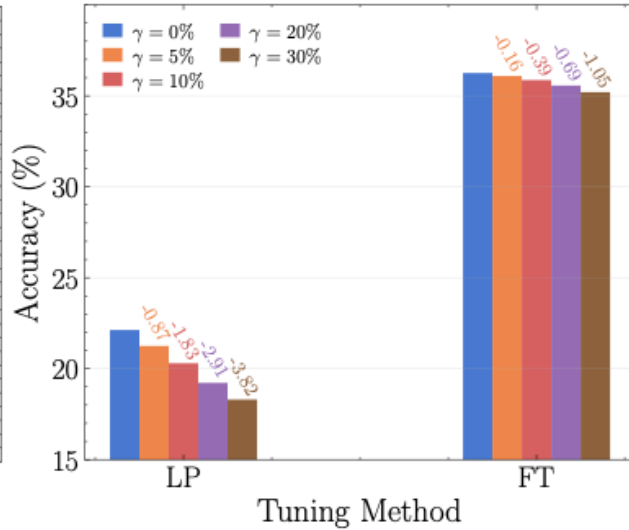
- Different tuning methods on ID tasks present similar trends
 - up to 5% or 10% can benefit ID performance
- Differences between clean and noisy models become smaller
 - with more pre-trained parameters modified at downstream tasks

OOD Eval. with Different Tuning Methods

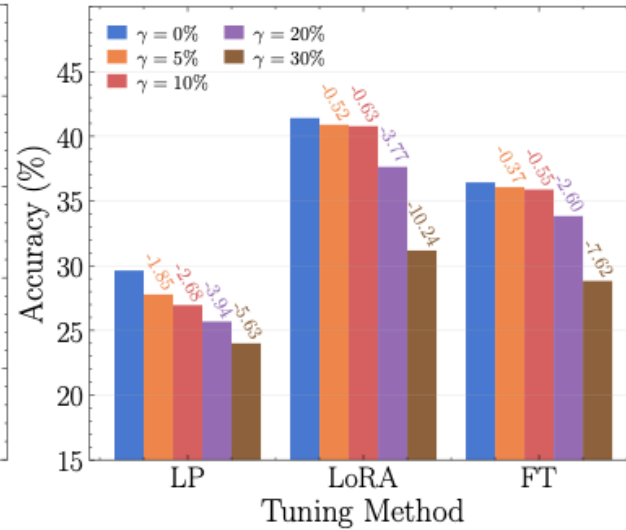
R-50 IN-1K FS



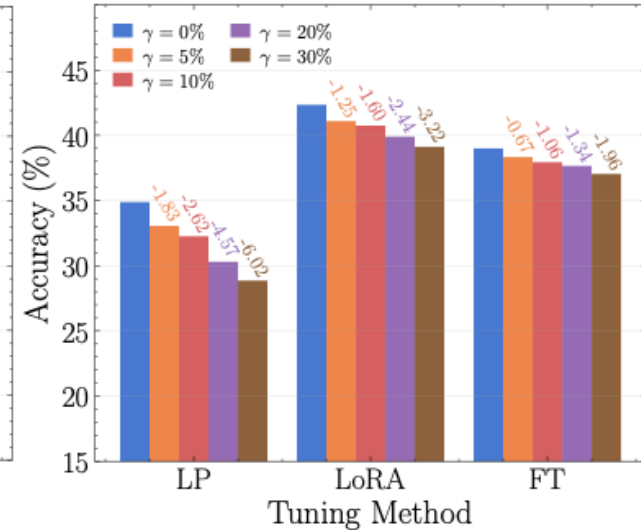
R-50 YFCC15M CLIP



ViT IN-1K FS



ViT YFCC15M+CC12M CLIP



- Different tuning methods on OOD tasks present similar trends
 - pre-train noise consistently hurts the performance
- Differences between clean and noisy models become smaller
 - with more pre-trained parameters modified at downstream tasks

Detection and Segmentation Tasks

TABLE 4: Object detection results on COCO 2017 of IN-1K ResNet-50 noisy FS pre-trained models.

Detection	Noise (%)	AP ^{box}	AP ₅₀ ^{box}	AP ₇₅ ^{box}
Faster R-CNN [19]	0	38.5	59.8	41.7
	5	38.6	60.1	41.9
	10	38.6	60.0	41.9
	20	38.4	59.7	41.6
	30	37.9	59.1	40.9
RetinaNet [20]	0	38.3	58.2	40.9
	5	38.4	58.4	40.9
	10	38.4	58.1	41.1
	20	37.9	57.7	40.4
	30	37.0	56.8	39.1

TABLE 5: Instance segmentation results on COCO 2017 of IN-1K ResNet-50 noisy FS pre-trained models.

Detection	Noise (%)	AP ^{mask}	AP ₅₀ ^{mask}	AP ₇₅ ^{mask}
Mask R-CNN [21]	0	31.3	51.3	33.0
	5	31.4	51.3	33.2
	10	31.3	51.3	32.9
	20	31.2	51.1	32.8
	30	30.30	49.9	32.1
SOLOv2 [140]	0	32.2	52.7	33.6
	5	32.7	53.2	34.2
	10	32.4	52.8	33.9
	20	32.0	52.2	33.6
	30	31.4	51.3	32.5

- Evaluate IN-1K noisy pre-trained on COCO Detection and Segmentation
- Slight pre-training noise can also benefit other downstream tasks than classification

Feature Space Analysis

Empirical Study

Singular Values Analysis

- Where do the superior ID performance (with slight noise) and the inferior OOD performance stem from?
- We conduct SVD on features of pre-trained models on downstream tasks
 - **Singular Value Entropy (SVE)**: measures the flatness of singular value distribution

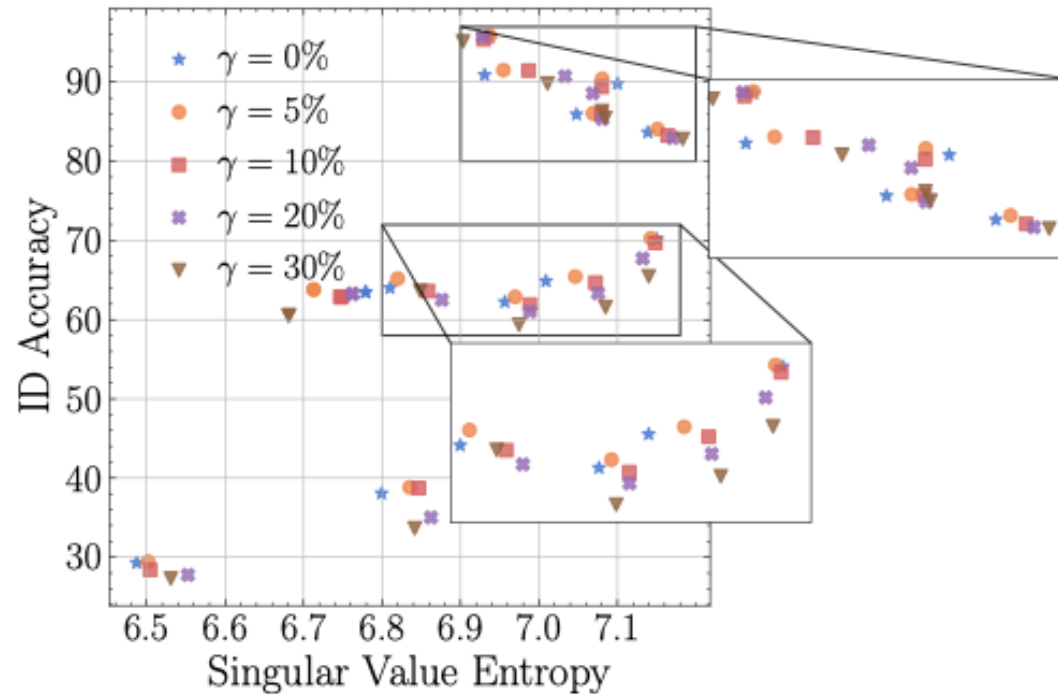
$$\text{SVE} = - \sum_{i=1}^D \frac{\sigma_i}{\sum_{j=1}^D \sigma_j} \log \frac{\sigma_i}{\sum_{j=1}^D \sigma_j}$$

- **Largest Singular Value Ratio (LSVR)**: measures the ratio of the largest singular value

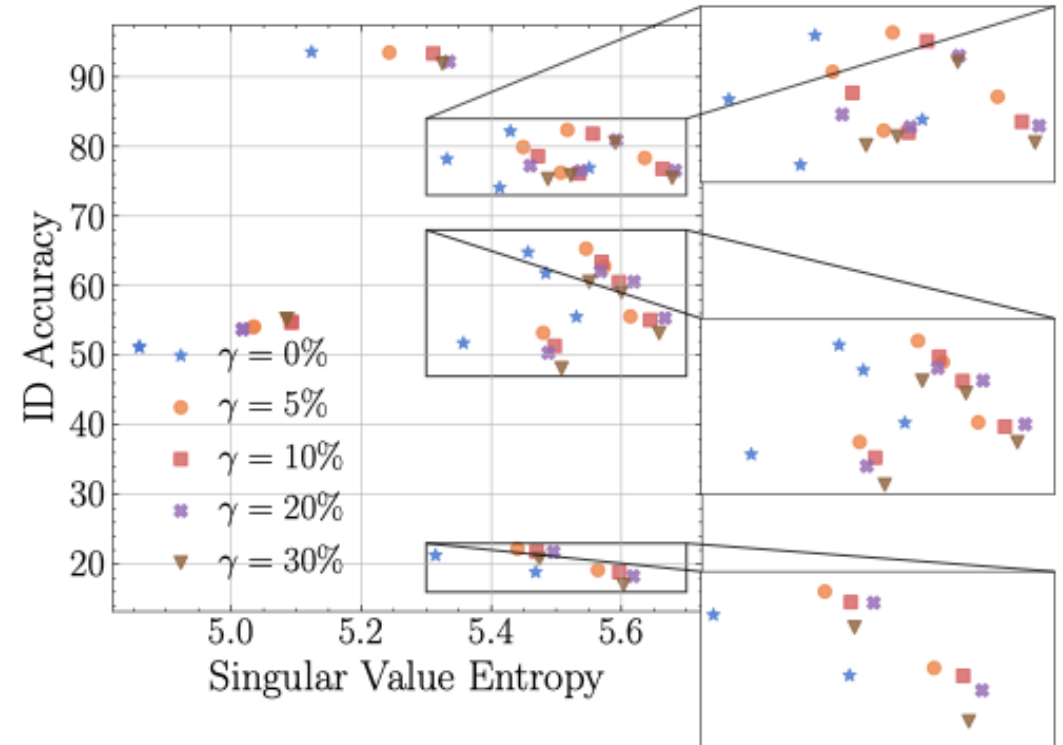
$$\text{LSVR} = - \log \frac{\sigma_1}{\sum_{i=1}^D \sigma_i}$$

ID – Singular Value Entropy

R-50 ImageNet-1K Fully Supervised

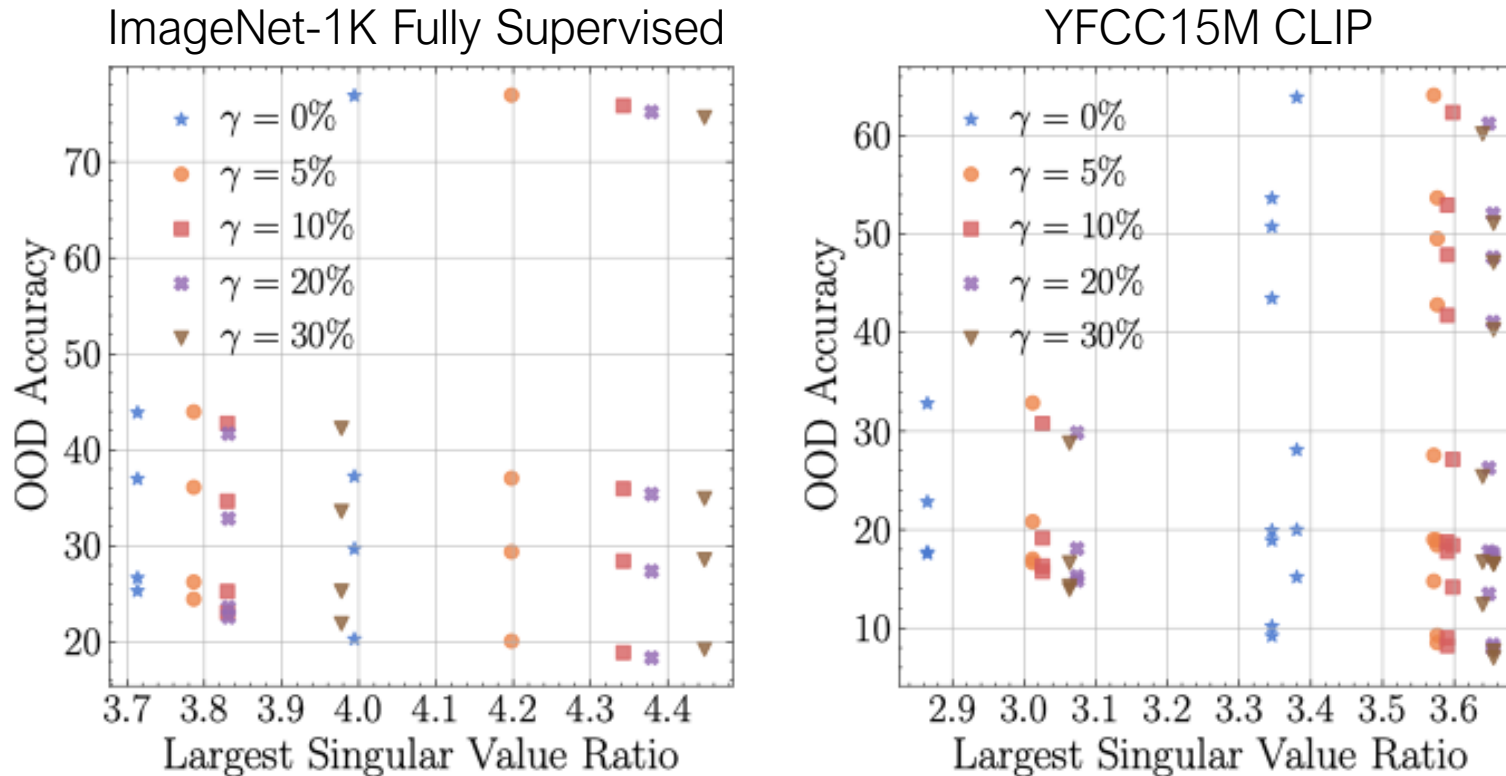


R-50 YFCC15M CLIP



- SVE and ID accuracy first increases then decreases, as the noise ratio increases
- Slight pre-training noise encourages the model to use **more capacity** to **fit the noise**
- A higher dimension of feature space, better-initialized features at the downstream
- Noise further increases, more dimensions fitting the noise, less useful features at downstream

OOD – Largest Singular Value Ratio



- LSVR consistently increases and OOD consistently decreases, as the noise ratio increases
- More capacity in feature space is used for fitting noise, and **less transferable/dominant singular vectors** are learned during pre-training

Mitigating the Noise on Downstream

- We propose a **black-box fine-tuning** method
 - with an MLP projection head and a linear classification layer
 - MLP is used for affine transformation of pre-trained features \mathbf{F} to get \mathbf{Z}
- NMTune defines 3 regularization terms during black-box fine-tuning
 - encouraging consistency between pre-trained features and MLP-transformed features

$$\mathcal{L}_{\text{MSE}} = \left\| \frac{\mathbf{F}}{\|\mathbf{F}\|_2} - \frac{\mathbf{Z}}{\|\mathbf{Z}\|_2} \right\|_2^2$$

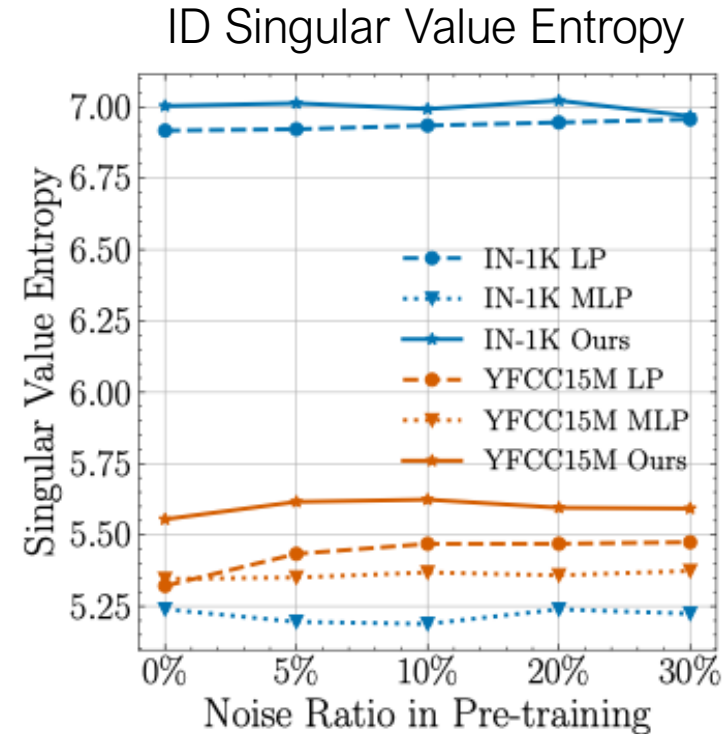
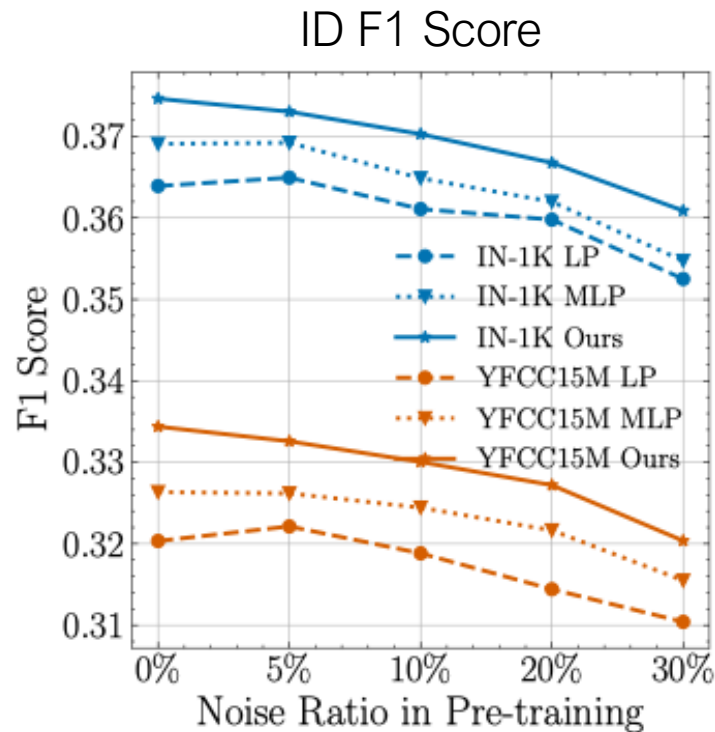
- minimizing the covariance matrix of MLP-transformed features

$$\mathcal{L}_{\text{COV}} = \frac{1}{D} \sum_{i \neq j} [C(\mathbf{Z})]_{i,j}^2$$

- maximizing the largest singular value ratio of MLP-transformed features

$$\mathcal{L}_{\text{SVD}} = -\frac{\sigma_1}{\sum_j^D \sigma_{j=1}}$$

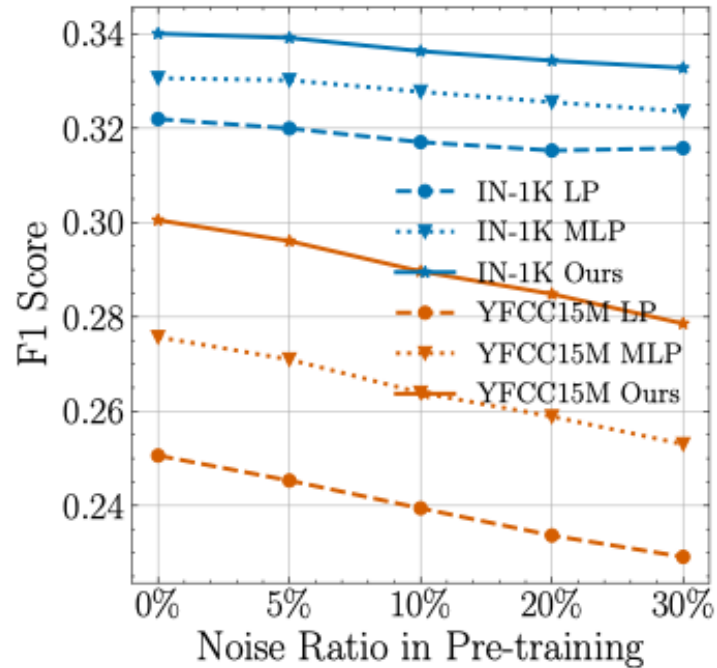
NMTune for ID tasks



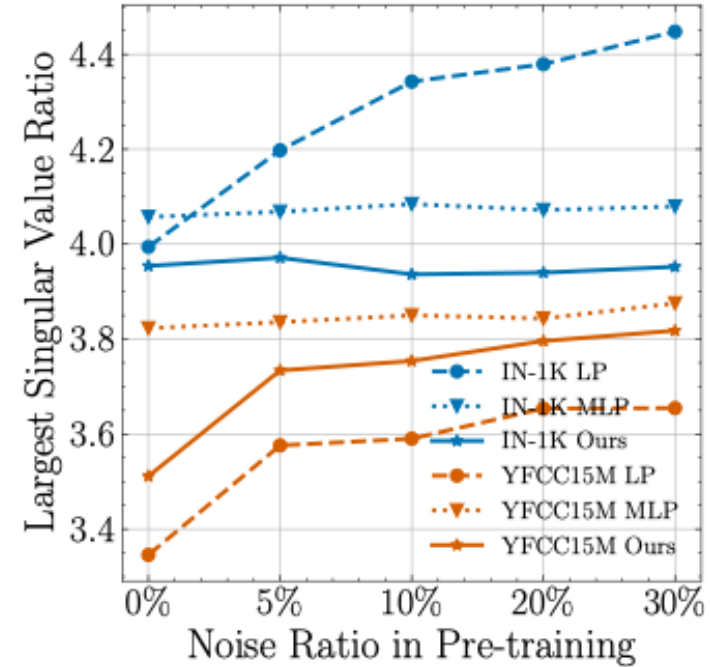
- Our method helps improve F1 score and SVE for ID tasks for both noisy ImageNet-1K and YFCC15M pre-trained models
- Adding MLP only helps with F1 but produces lower SVE

NMTune for OOD tasks

OOD F1 Score

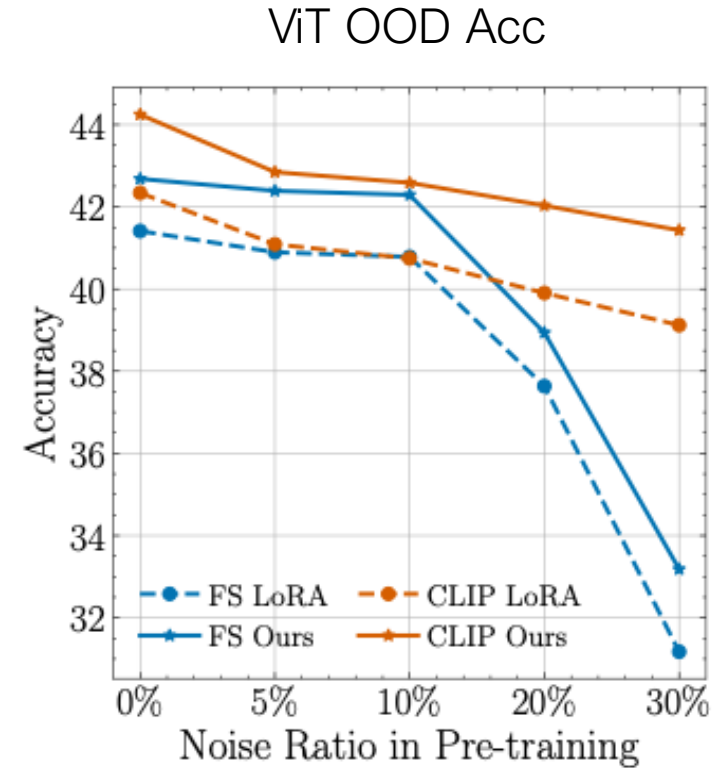
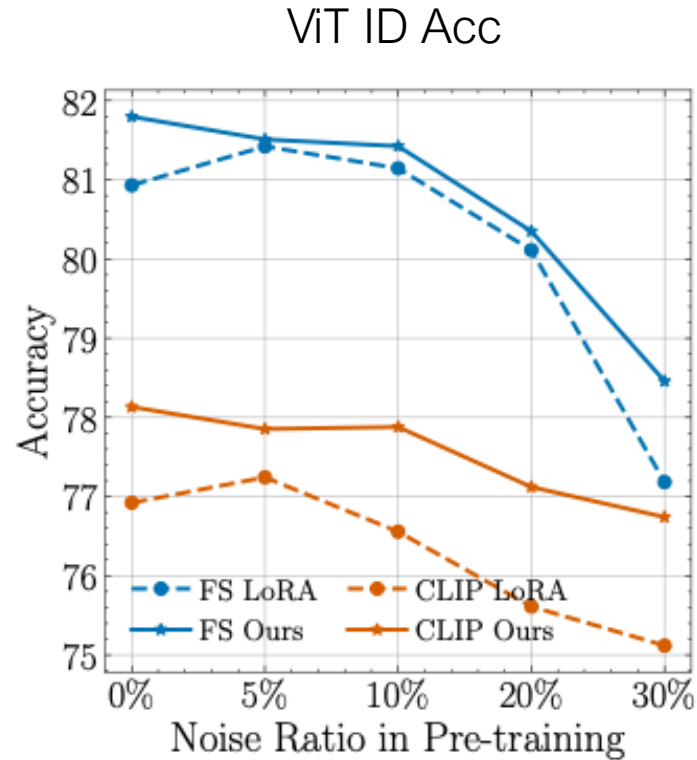


OOD Largest Singular Value Ratio



- Our method helps improve F1 score for OOD tasks
- Our method produces more consistent LSVR across noise ratios (MLP also does)

NMTune for LoRA



- NMTune also can be applied with LoRA to mitigate the pre-training noise

Practical Large Models

- Vision Models
 - JFT300M Semi-Supervised Pre-trained EfficientNet-B3
 - ImageNet-21K Fully-Supervised Pre-trained ResNetv2-152x2
 - ImageNet-21K Fully-Supervised Pre-trained Swin-L
 - Laion-2B CLIP Pre-trained ConvNext-L
 - Laion-2B CLIP Pre-trained ViT-L
 - ID: 14 datasets, OOD: DomainNet
- Language Models
 - BERT-L, RoBERTa-L, GPT-2, text-ada-002 embedding API
 - ID: GLUE, OOD: GLUE-X

Practical Large Models

Table 1: Results on popular vision models that are pre-trained on noisy datasets. We use 14 in-domain (ID) and 4 out-of-domain (OOD) tasks.

Pre-trained Model	Tuning Method	In-Domain		Out-of-Domain	
		Acc.	F1	Acc.	F1
JFT300M	LP	76.72	0.3815	44.13	0.3594
Semi-Supervised	MLP	76.87	0.3833	45.95	0.3624
EfficientNet-B3	Ours	77.63	0.3874	46.84	0.3654
ImageNet-21K	LP	77.51	0.3718	40.82	0.3062
Fully Supervised	MLP	77.58	0.3726	41.73	0.3053
ResNetv2-152x2	Ours	78.43	0.3862	42.42	0.3100
ImageNet-21K	LP	81.91	0.4092	50.88	0.3838
Fully Supervised	MLP	82.51	0.4128	51.21	0.3811
Swin-L	Ours	84.16	0.4177	52.35	0.3901
Laion-2B	LP	88.86	0.4432	66.86	0.4253
CLIP	MLP	88.53	0.4417	68.43	0.4304
ConvNext-L	Ours	89.48	0.4457	70.30	0.4367
Laion-2B	LP	86.85	0.4328	66.89	0.4208
CLIP	MLP	87.23	0.4375	69.50	0.4221
ViT-L	Ours	88.57	0.4414	70.47	0.4246

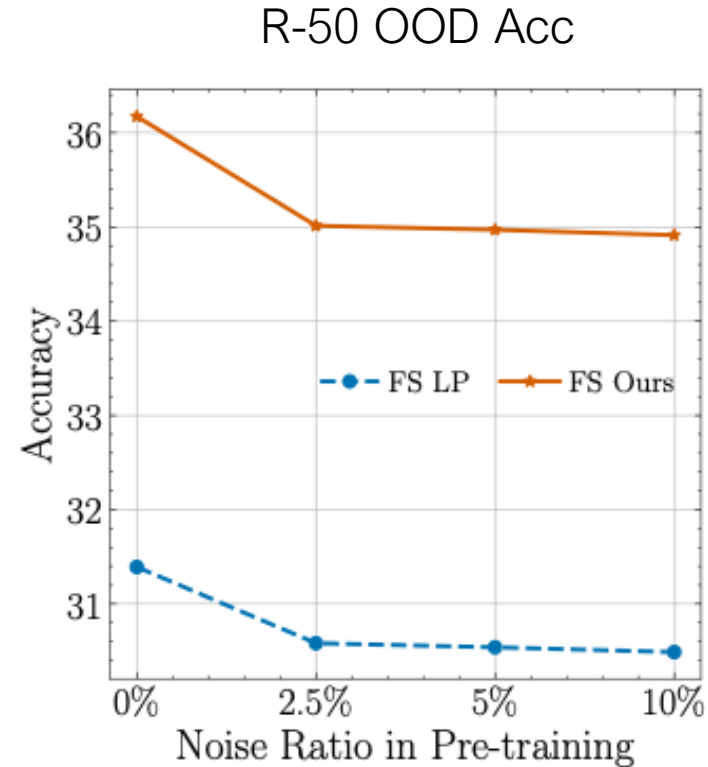
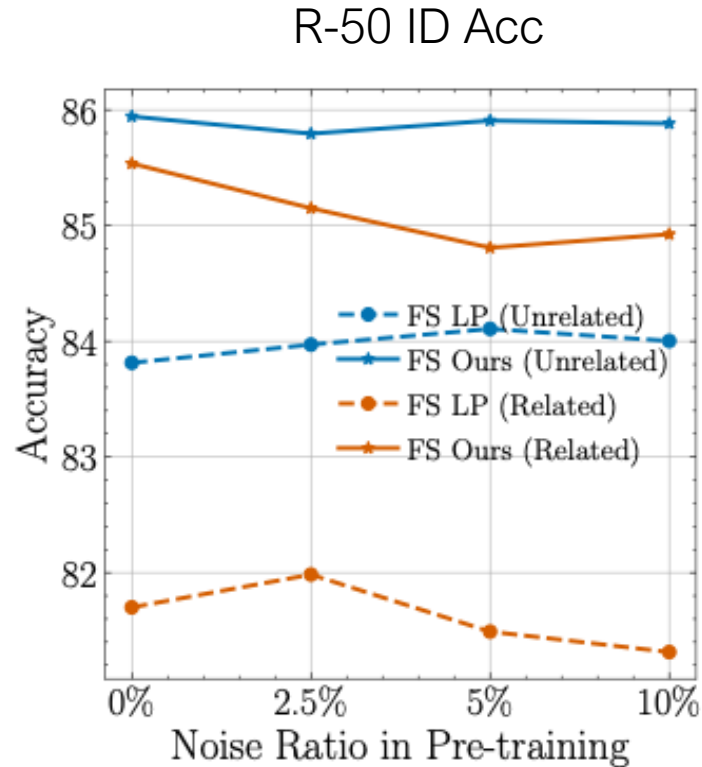
Table 2: Evaluation of our method on language models in practice that are pre-trained on noisy datasets. We use GLUE for in-domain (ID) tasks and GLUE-X for out-of-domain (OOD) tasks.

Pre-trained Model	Tuning Method	In-Domain	Out-of-Domain
BERT-L	LP	69.44	50.65
	MLP	69.78	50.62
	Ours	70.26	51.63
RoBERTa-L	LP	69.75	44.55
	MLP	70.27	45.22
	Ours	70.97	47.01
GPT-2	LP	58.67	36.68
	MLP	58.44	37.24
	Ours	59.34	39.07
text-ada-002	LP	56.96	44.06
	MLP	63.89	51.30
	Ours	65.99	53.48

Asymmetric Pre-training Noise

- Previous experiments mainly involve **random** pre-training noise
 - noise can exist in all classes/concepts uniformly
- We also study **asymmetric noise** in ImageNet-1K
 - find overlapped classes in IN-1K with CIFAR-100 using wordnet
 - introduce noise only within these overlapped classes
- Downstream linear probing evaluation:
 - noise-related ID: CIFAR-10, CIFAR-100
 - noise-unrelated ID: Food-101, Caltech101, EuroSAT
 - OOD: DomainNet

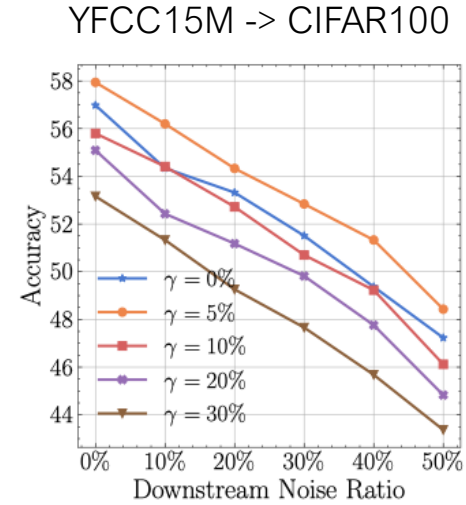
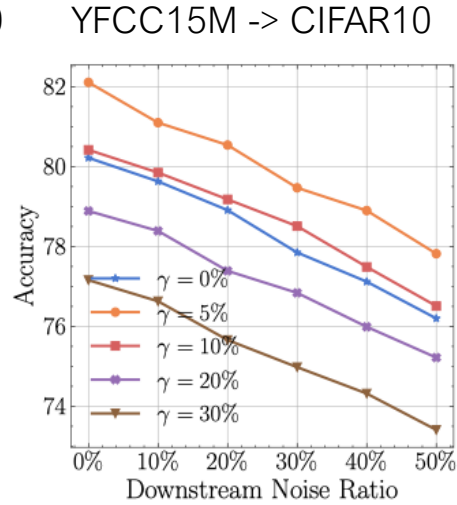
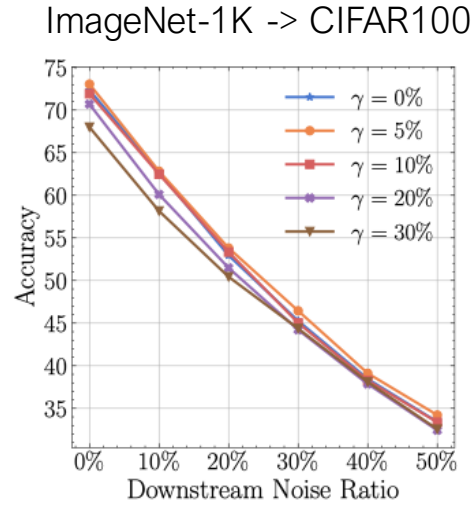
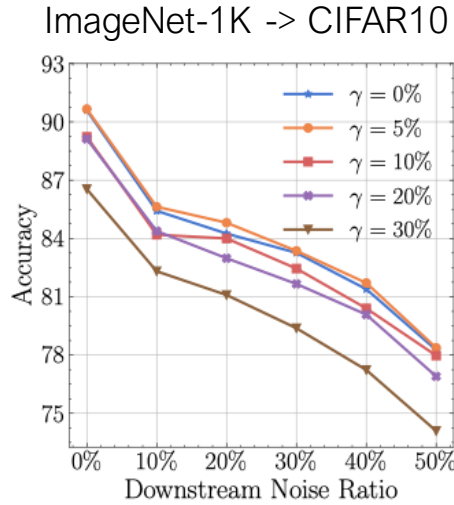
Asymmetric Pre-training Noise



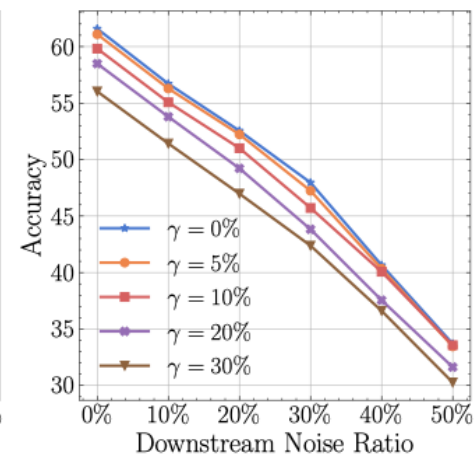
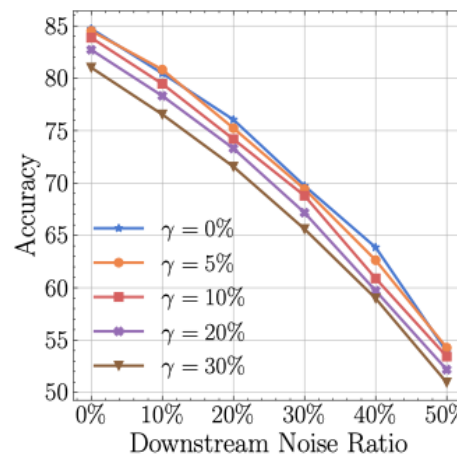
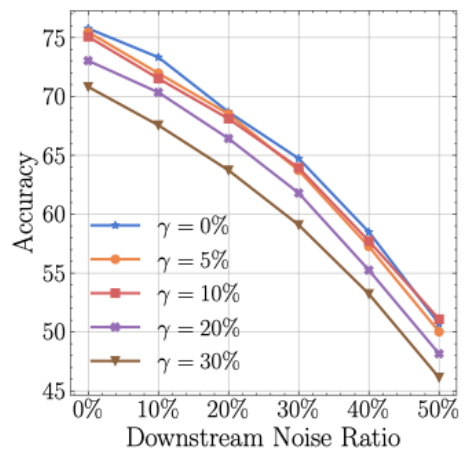
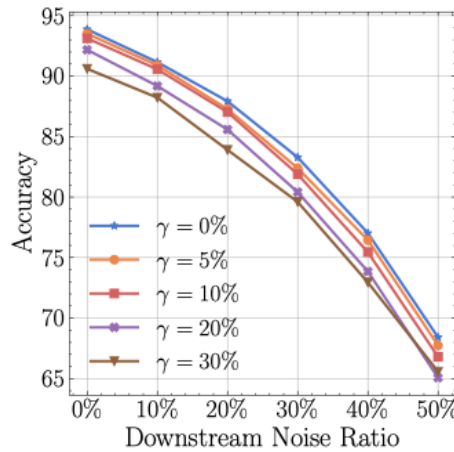
- Previous observations still manifest on asymmetric pre-training noise

Combining with Noisy Label Learning

Linear Probe



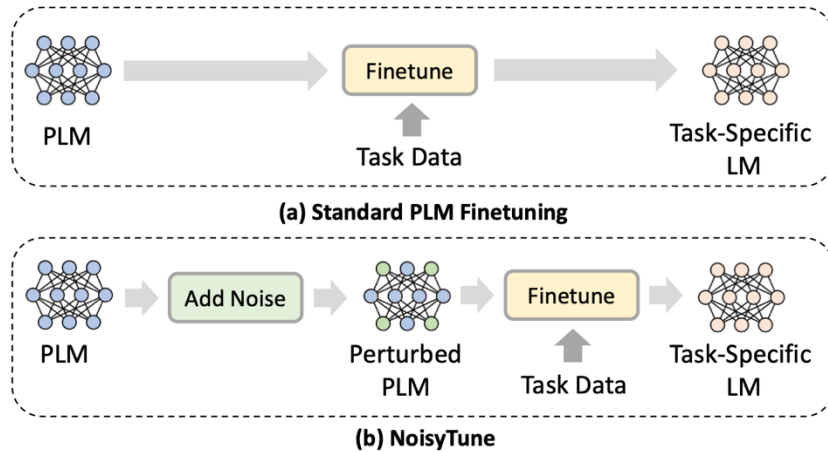
NMTune



- Similar observation holds on NLL and NMTune also helps

Related Works on Pre-training Noise/Data

- NoisyTune



- NEFTune

Algorithm 1 NEFTune: Noisy Embedding Instruction Finetuning

Input: $\mathcal{D} = \{x_i, y_i\}_1^N$ tokenized dataset, embedding layer $\text{emb}(\cdot)$, rest of model $f_{/\text{emb}}(\cdot)$, model parameters θ , loss \cdot , optimizer $\text{opt}(\cdot)$

NEFT Hyperparameter: base noise scale $\alpha \in \mathbb{R}^+$

Initialize θ from a pretrained model.

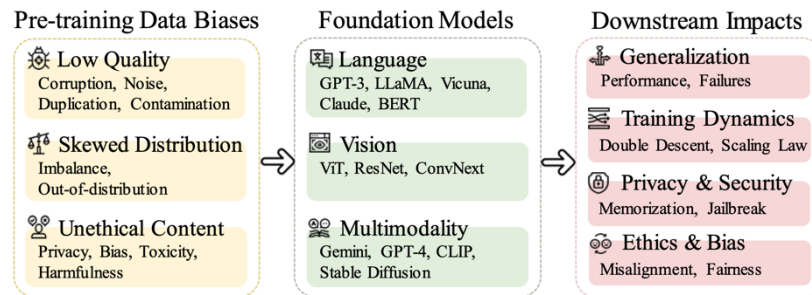
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repeat  $(X_i, Y_i) \sim \mathcal{D}$ 
     $X_{\text{emb}} \leftarrow \text{emb}(X_i), \mathbb{R}^{B \times L \times d}$ 
     $\epsilon \sim \text{Uniform}(-1, 1), \mathbb{R}^{B \times L \times d}$ 
     $X'_{\text{emb}} \leftarrow X_{\text{emb}} + (\frac{\alpha}{\sqrt{Ld}})\epsilon$ 
     $\hat{Y}_i \leftarrow f_{/\text{emb}}(X'_{\text{emb}})$ 
     $\theta \leftarrow \text{opt}(\theta, \text{loss}(\hat{Y}_i, Y_i))$ 
until Stopping criteria met/max iterations.
    
```

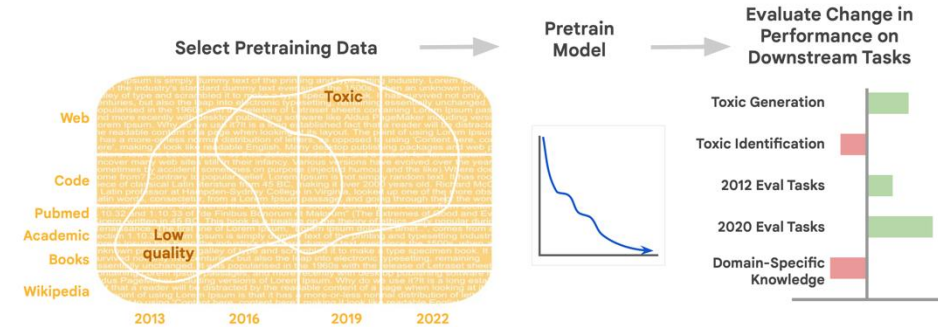
▷ sample a minibatch of data and labels
 ▷ batch size B , seq. length L , embedding dimension d
 ▷ sample a noise vector
 ▷ add scaled noise to embeds a
 ▷ make prediction at noised embeddings
 ▷ train step, e.g., grad descent

^aIf sequence lengths in a batch are not equivalent, then L is a vector $\in \mathbb{Z}_{>0}^B$ and the scaling factor (α/\sqrt{Ld}) is computed independently for each sequence in batch.

- Catastrophic Inheritance



- Pre-trainer's Guide to LLM training data



Chuhan Wu, et al. NoisyTune: A Little Noise Can Help You Finetune Pretrained Language Models Better.

Neel Jain, et al. NEFTUNE: Noisy Embedding Improve Instruction Fine-Tuning.

Hao Chen et al. On catastrophic inheritance of large foundation models.

Shayne Longpre et al. A pre-trainer's guide to training data.

Conclusion

- We propose **Noisy Model Learning**
 - A novel research topic for studying and mitigating the pre-training noise
- We found:
 - Slight noise in pre-training benefits ID tasks, agnostic to model **architectures**, pre-training proxy **objectives**, pre-training **noise types**, downstream **tuning methods**, and downstream **applications**
 - However, pre-training noise always hurts OOD tasks
 - Malicious effects of pre-training noise can be mitigated at downstream tasks through NMTune
- Future work includes other pre-training paradigms and other types of pre-training biases

Thanks

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